### **UNIVERSITY COLLEGE LONDON**

University of London

## **EXAMINATION FOR INTERNAL STUDENTS**

For The Following Qualifications:-

B.Sc. M.Sci.

**Mathematics B3D: Pure Mathematics** 

COURSE CODE	: MATHB03D
UNIT VALUE	: 0.50
DATE	: 30-APR-03
TIME	: 10.00
TIME ALLOWED	: 2 Hours

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# **TURN OVER**

All questions may be attempted but only marks obtained on the best five solutions will count.

The use of an electronic calculator is not permitted in this examination.

1. Let V be the set of vectors  $\mathbf{x}$  in  $\mathbf{R}^5$  satisfying the following system of equations :

ſ	$x_1$	$-x_2$		$-x_4$	$+x_{5}$	=	0
ł	$x_1$	$-x_2$	$-x_3$			=	0
J	$x_1$	$-x_2$	$+x_{3}$	$-2x_{4}$	$+2x_{5}$	=	0

Find  $\dim(V)$  and write down a basis for V.

By applying the Gram-Schmidt process, find an orthonormal basis for V.

2. The Fourier series of the real valued function f(x) defined on  $[-\pi,\pi]$  is

$$f(x) \sim C(f) + \sum_{m \ge 1} A_m(f) \cos(mx) + \sum_{m \ge 1} B_m(f) \sin(mx).$$

(i) Write down formulae for the Fourier coefficients C(f),  $A_m(f)$  and  $B_m(f)$  as integrals involving f.

- (ii) Show that  $A_m(x^{2n}) = -\left(rac{2n}{m}
  ight) B_m(x^{2n-1}).$
- (iii) The Fourier series for the function f(x) = x is

$$x \sim \sum_{m \ge 1} (-1)^{m+1} \frac{2}{m} \sin(mx);$$

Find the constant  $C(x^2)$ , and hence write down the Fourier series for the function

$$f(x) = x^2.$$

(iv) By integrating term by term, or otherwise, find the Fourier series of the function

$$f(x) = x^3 - \pi^2 x.$$

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3. Find the characteristic polynomial of the matrix  $A = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$ .

Hence find

- (i) an orthogonal basis of eigenvectors of A;
- (ii) an invertible  $3 \times 3$  matrix P such that  $P^{-1}AP$  is diagonal.

If the matrix P is not orthogonal, explain briefly how to modify it until it becomes orthogonal.

4. Let  $g\begin{pmatrix} x_1\\ x_2 \end{pmatrix}$  be a real valued function of two variables  $x_1, x_2$ .

Explain what is meant by

- (i) a critical point of g;
- (ii) a nondegenerate critical point.

Describe the possible types of behaviour of g near a nondegenerate critical point.

Let 
$$g\begin{pmatrix} x_1\\ x_2 \end{pmatrix} = 6x_1^3 + x_2^2 + 6x_1x_2.$$

Show that g has a critical point at  $\begin{pmatrix} 1 \\ -3 \end{pmatrix}$ , and classify it according to type. Show that g has precisely one other critical point. Find it, and classify it according to type.

5. Find a particular solution to the differential equation

$$\frac{d^2y}{dx^2} + \frac{dy}{dx} - 6y = 5\sin(x) - 15\cos(x).$$

Hence write down the general solution to this equation. A solution y(x) to the above equation satisfies

$$y(0) = 5$$
;  $y'(0) = -5$ .

Find the explicit form of y(x), and also the value of y''(0).

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6. By means of transformation to polar coordinates

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$$x_1 = r\cos(\theta)$$
;  $x_2 = r\sin(\theta)$ ,

find expressions for the following differential operators in terms of  $r, \theta$ .

(i) 
$$\frac{\partial}{\partial x_1}$$
; (ii)  $\frac{\partial}{\partial x_2}$ ; (iii)  $x_1 \frac{\partial}{\partial x_1} + x_2 \frac{\partial}{\partial x_2}$ .  
A function  $f\begin{pmatrix}x_1\\x_2\end{pmatrix}$  satisfies the differential equation  
 $\left(x_1\frac{\partial}{\partial x_1} + x_2\frac{\partial}{\partial x_2}\right)f = (x_1^2 + x_2^2)\exp(\sqrt{x_1^2 + x_2^2});$ 

moreover, it is known that the value of f at  $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$  is independent of  $\theta$ . Find the explicit expression for  $f\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$  in terms of  $x_1, x_2$  if  $f\begin{pmatrix} 0 \\ 0 \end{pmatrix} = 1$ .

7. Explain what is meant by the *commutator*  $[L_1, L_2]$  of linear operators  $L_1, L_2$ . Find expressions for

(i) 
$$\left[\frac{d}{dx}, e^x\right]$$
; (ii)  $\left[\frac{d^2}{dx^2}, e^x\right]$ .

The angular momentum operator in the (i, j)-plane is

$$L_{ij} = x_i \frac{\partial}{\partial x_j} - x_j \frac{\partial}{\partial x_i}.$$

- (iii) Show that  $[L_{12}, L_{23}] = L_{13}$ .
- (iv) Find also an expression for

$$\left[ x_1^3 \frac{\partial}{\partial x_2} , x_2^3 \frac{\partial}{\partial x_1} \right].$$

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