## **UNIVERSITY COLLEGE LONDON**

University of London

## **EXAMINATION FOR INTERNAL STUDENTS**

For The Following Qualification:-

M.Eng.

**Chemical Eng E852: Advanced Process Engineering** 

COURSE CODE

: CENGE852

UNIT VALUE

: 0.50

DATE

: 11-MAY-04

TIME

: 10.00

TIME ALLOWED

: 3 Hours

Answer FOUR questions. Each question carries a total of 25 marks, distributed as shown []. Only the FIRST FOUR ANSWERS will be marked.

1.

- a) The basic iterative algorithm for gradient based algorithms for solving unconstrained optimisation problems is given below:
  - 1. Choose initial point
  - 2. Determine step direction
  - 3. Determine step length
  - 4. Update information
  - 5. If convergence attained stop

if not return to step 2

Discuss each of these steps in turn giving mathematical formulations where possible that can be used in implementation. [8]

b) Using a Newton based algorithm generate the first iteration without line search for the following problem starting from  $x^0 = \begin{bmatrix} -1 & 1 \end{bmatrix}^T$ 

$$f(x) = x_1^3 + x_1x_2 - x_2^2x_1^2$$

[10]

- What condition is required to ensure that steps generated by Newton type methods are descent steps?
- d) What properties of the Hessian matrix does the BFGS (Broyden-Fletcher-Goldfarb-Shanno) update retain from iteration to iteration? Explain why each property is important. [5]

2.

- a) The basic steps of the Successive Quadratic Programming algorithm for solving constrained optimisation problems are as follows
  - 1. Choose an initial feasible point
  - 2. Solve the Quadratic programming problem for the step direction
  - 3. Line search
  - 4. Solve for the Lagrange multipliers
  - 5. Evaluate the gradients. If the point is a Kuhn Tucker point then stop.
  - 6. Update the Hessian approximation using the BFGS (Broyden-Fletcher-Goldfarb-Shanno) update
  - 7. Set k = k+1 and return to step 2.
  - i) What are the Kuhn Tucker conditions?
  - ii) What is meant by a Quadratic Programming Problem?
  - iii) Explain the significance of the Lagrange multipliers?
  - iv) Give an example of a method that may be used for the line search.

[10]

CONTINUED

b) The cost of constructing a distillation column can be written as

$$C = C_p AN + C_s HAN + C_f + C_L$$

where

C = total cost	£
$C_p = \cos t$ per square metre of plate area	$500 \text{ £ m}^{-2}$
N = number of plates	_
$C_s = \text{cost of shell}$	200 £ m <sup>-3</sup>
H = distance between plates	0.5 m
A = column cross sectional area	$m^2$
$C_L = \text{cost of reflux pump}$	£
$C_f$ = other fixed costs	£30000
L = reflux rate	kg m <sup>-3</sup>
D = distillate rate	kg m <sup>-3</sup> kg m <sup>-3</sup>

There are three further equations relating the variables

$$A = 0.01(L+D)$$

$$L/D = N/(N-5)$$

$$C_L = 5000 + 0.7L$$

Suggest two ways that the problem can be solved analytically (it is not necessary to solve the problem). [10]

c) What is meant by a non-convex constraint?

[5]

3.

a) The following is a mixed integer non-linear programming model involving bilinear products of continuous  $(X_{ij})$  and binary  $(Y_{ij})$  variables:

$$\min z = \sum_{i} \sum_{j} X_{ij}$$

subject to

$$\sum_{i} X_{ij} Y_{ij} \leq A_{i} \quad \forall i$$

$$Y_{ij} \in \{0,1\}$$

$$X_{ij} \geq 0$$

where  $A_i$  are given parameters.

**CONTINUED** 

Reformulate the model to a linear one by introducing new variables and additional constraints. [10]

b) Three power stations, A, B and C are committed to meeting the electricity demand over two different time periods during the day: 2500 MW during first period and 3500 MW during second period. A power station started in the first time period can be used in the second period without incurring any additional start-up cost. All power stations are turned off at the end the day. All related costs are shown in the table below:

Power Station	Max Capacity (MW)	Start-up Cost	Fixed Cost per Period	Cost per Period per MW used
Α	2000	6000	500	6
В	1500	4000	600	4
C	3000	2000	700	8

Formulate the above problem as a mixed integer linear programming (MILP) model without solving it so as to select which power stations should be working during each time period to minimise total cost. [15]

a) Formulate the following logical implication by a mixed integer linear set of constraints by using 0-1 variables:

If 
$$\sum_{i} A_i X_i \le B$$
 then  $\sum_{j} C_j Z_j \le D$ 

where X and Z are continuous variables; and  $A_i$ ,  $C_j$ , B and D are given parameters vectors. [10]

b) Consider the following two non-linear functions of positive  $X \ge 0$ :

$$f(X_1, X_2, X_3) = X_1 X_2 + X_1^{0.6} + \frac{X_1}{X_3}$$

$$g(X_1, X_2, X_3, X_4) = X_1 X_2 - X_3 X_4$$

i) Are these functions convex? Explain.

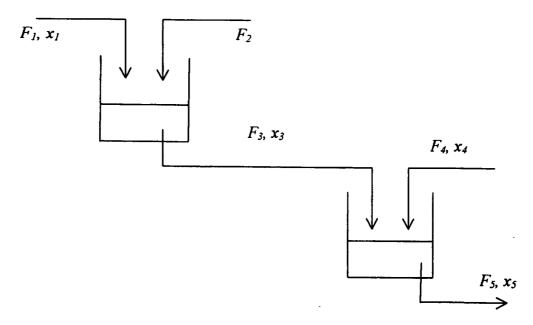
[3]

ii) Can the above functions be convexified by using suitable variable transformations? [4]

**CONTINUED** 

4.

- c) Let  $Y_{ij}$  denote the existence of a heat exchanger between streams i and j. Formulate the following statement as a set of constraints that are linear in  $Y_{ij}$ :
  - "A heat exchanger between streams i and j with area  $A_{ij}$  has a fixed cost F and a variable cost V, where  $V = C \times A_{ij}^{0.6}$  and C is a constant. The area of the exchanger should be larger than L and smaller than U" [8]
- 5.
- a) Many optimisation problems involving integer variables are solved iteratively (for example, Outer-Approximation). Usually, one common step of these solution algorithms is the introduction of an extra constraint (integer cut) at each iteration in the master problem (0-1 programming problem) in order to make infeasible the choice of binary vectors obtained from previous iterations. Develop such a constraint. [5]
- b) Consider the process shown in the diagram below. A methanol solution (methanol mole fraction:  $x_1$ ) with flowrate  $F_1$  is mixed in a tank with a pure methanol stream of flowrate  $F_2$ . The tank outlet has a flowrate  $F_3$  and methanol mole fraction  $x_3$ . It is mixed in a second tank with a 45% methanol solution (on a mole basis) of flowrate  $F_4$ . The product of the second tank has flowrate  $F_5$  and methanol mole fraction  $x_5$ .



## Process data:

$$F_1 = 10 \text{ kmol/hr}; x_4 = 0.45$$

Uncertain parameters: 
$$0.2 \le x_1 \le 0.4$$
 (nominal value: 0.3)

$$1 \le F_2 \le 3$$
 (nominal value: 2 kmol/hr)

Control variable:  $F_4 \ge 0$ 

**CONTINUED** 

Performance targets:  $F_5 \ge 13$  kmol hr<sup>-1</sup>  $0.4 \le x_5 \le 0.5$ 

- i) Derive a steady state model for this process which relates all inputs, uncertain parameters, and outputs. Formulate the model so that it contains inequality constraints only. [8]
- ii) Is the process feasible for the entire uncertainty region?
  - 1) if  $F_4 \le 30 \text{ kmol hr}^{-1}$
  - 2) if  $F_4 \le 24 \text{ kmol hr}^{-1}$

[12]

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## **END OF PAPER**

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