

UNIVERSITY OF SURREY[©]

B. Sc. Undergraduate Programmes in Mathematical Studies

Level HE3 Examination

Module MS303 CURVES AND SURFACES

Time allowed – 2 hrs

Autumn Semester 2007

Attempt **THREE** questions

If a candidate attempts more than **THREE** questions only the best **THREE** questions will be taken into account.

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Question 1

Let $\gamma(s)$ be a *unit-speed* space curve and suppose that the curvature $\kappa(s) > 0$ for all s . Let

$$\mathbf{t}(s) = \dot{\gamma}(s), \quad \mathbf{n}(s) = \frac{\ddot{\gamma}(s)}{\|\ddot{\gamma}(s)\|}, \quad \mathbf{b}(s) = \mathbf{t}(s) \times \mathbf{n}(s).$$

The Frenet-Serret equations satisfied by the moving frame $(\mathbf{t}(s), \mathbf{n}(s), \mathbf{b}(s))$ are

$$\dot{\mathbf{t}} = \kappa \mathbf{n}, \quad \dot{\mathbf{n}} = -\kappa \mathbf{t} + \tau \mathbf{b}, \quad \dot{\mathbf{b}} = -\tau \mathbf{n},$$

where $\kappa(s)$ and $\tau(s)$ are the curvature and torsion respectively.

- (a) Express the *third derivative* of $\gamma(s)$ in terms of the moving frame

$$\ddot{\gamma}(s) = a_1(s)\mathbf{t}(s) + a_2(s)\mathbf{n}(s) + a_3(s)\mathbf{b}(s).$$

Find expressions for the scalar-valued functions $a_1(s), a_2(s), a_3(s)$ in terms of the curvature $\kappa(s)$, torsion $\tau(s)$ and $\dot{\kappa}$. [8]

- (b) Using the expression for $\ddot{\gamma}$ derived in (a), show that

$$\dot{\gamma} \cdot (\ddot{\gamma} \times \ddot{\gamma}) = \tau \kappa^2.$$

[5]

- (c) Show that

$$\dot{\gamma} \cdot (\ddot{\gamma} \times \ddot{\gamma}) = -\kappa \dot{\mathbf{t}} \cdot \dot{\mathbf{b}}.$$

[4]

- (d) Suppose that there exists a non-zero constant vector $\mathbf{m} \in \mathbb{R}^3$ such that $\mathbf{m} \cdot \dot{\gamma}(s) = 0$ for all s . Show that the torsion $\tau(s)$ of the curve is zero for all s . [8]

Question 2

Let M be a surface with regular coordinate chart (\mathbf{x}, U) , $U \subset \mathbb{R}^2$. Take the unit normal at each point to be

$$\mathbf{n}(u, v) = \frac{\mathbf{x}_u \times \mathbf{x}_v}{\|\mathbf{x}_u \times \mathbf{x}_v\|}, \quad (u, v) \in U.$$

Assume that $\mathbf{x}_u \cdot \mathbf{x}_v = 0$ at all points on the surface.

- (a) Expressing the derivative of $\mathbf{n}(u, v)$ as

$$\begin{aligned} \mathbf{n}_u &= -a_{11}\mathbf{x}_u - a_{12}\mathbf{x}_v - a_{13}\mathbf{n} \\ \mathbf{n}_v &= -a_{21}\mathbf{x}_u - a_{22}\mathbf{x}_v - a_{23}\mathbf{n}. \end{aligned}$$

Explain why $a_{13} = a_{23} = 0$ and find expressions for $a_{11}, a_{12}, a_{21}, a_{22}$ in terms of

$$E = \mathbf{x}_u \cdot \mathbf{x}_u, \quad G = \mathbf{x}_v \cdot \mathbf{x}_v, \quad L = \mathbf{n} \cdot \mathbf{x}_{uu}, \quad M = \mathbf{n} \cdot \mathbf{x}_{uv}, \quad N = \mathbf{n} \cdot \mathbf{x}_{vv}. \quad [8]$$

- (b) Let $\gamma(t) = \mathbf{x}(u(t), v(t))$ be a regular curve in the surface passing through a point \mathbf{p} . Show that second derivative of the curve at the point \mathbf{p} satisfies

$$\mathbf{n} \cdot \ddot{\gamma} = \Pi_p(\dot{\mathbf{w}}, \dot{\mathbf{w}}), \quad \mathbf{w}(t) := \begin{pmatrix} u(t) \\ v(t) \end{pmatrix},$$

$$\text{where } \Pi_p(\dot{\mathbf{w}}, \dot{\mathbf{w}}) = \dot{u}^2 L + 2\dot{u}\dot{v}M + \dot{v}^2 N. \quad [6]$$

- (c) How are the eigenvalues of the matrix $\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$ related to curvature? [2]
- (d) Define what it means for a point $\mathbf{p} \in M$ to be *umbilic*, and relate this property to the eigenvalues of \mathbf{A} . [2]
- (e) Suppose \mathbf{p} is an umbilic point, and let $\gamma(t) = \mathbf{x}(u(t), v(t))$ be a curve passing through \mathbf{p} . Show that the normal curvature at \mathbf{p} can be expressed in the form

$$\kappa_n = \frac{1}{\ell^2} \mathbf{n} \cdot \ddot{\gamma}, \quad \text{with } \ell = \sqrt{E\dot{u}^2 + G\dot{v}^2}. \quad [7]$$

Question 3

Let M be a *ruled surface* in \mathbb{R}^3 . Ruled surfaces can be expressed in terms of a single coordinate chart (\mathbf{x}, U) with

$$\mathbf{x}(u, v) = \boldsymbol{\gamma}(u) + v \boldsymbol{\delta}(u),$$

where $\boldsymbol{\gamma}(u)$ and $\boldsymbol{\delta}(u)$ are given space curves, and

$$U = \{ (u, v) \in \mathbb{R}^2 : 0 < u < \infty, v \in \mathbb{R} \}.$$

(a) State conditions on $\boldsymbol{\gamma}(u)$ and $\boldsymbol{\delta}(u)$ for the coordinate chart to be *regular*. [5]

(b) State a formula for the Gaussian curvature in terms of E, F, G and L, M, N where

$$E = \mathbf{x}_u \cdot \mathbf{x}_u, \quad F = \mathbf{x}_u \cdot \mathbf{x}_v, \quad G = \mathbf{x}_v \cdot \mathbf{x}_v, \quad L = \mathbf{n} \cdot \mathbf{x}_{uu}, \quad M = \mathbf{n} \cdot \mathbf{x}_{uv}, \quad N = \mathbf{n} \cdot \mathbf{x}_{vv},$$

where \mathbf{n} is the unit normal vector. [4]

(c) Suppose that $\boldsymbol{\gamma}(u)$ is a unit speed curve, $\boldsymbol{\delta}(u)$ has unit length,

$$\dot{\boldsymbol{\gamma}}(t) \cdot \boldsymbol{\delta}(t) = 0 \quad \text{and} \quad \dot{\boldsymbol{\gamma}}(t) \cdot \dot{\boldsymbol{\delta}}(t) = 0.$$

Determine expressions for the coefficients E, F and G . [8]

(d) Prove that the Gaussian curvature of a ruled surface with a regular coordinate chart is less than or equal to zero at every point on the surface. [8]

Question 4

Consider a torus M in \mathbb{R}^3 with regular coordinate chart (\mathbf{x}, U) of the form

$$\mathbf{x}(u, v) = ((R + r \cos u) \cos v, (R + r \cos u) \sin v, r \sin u), \quad R > r > 0,$$

$U = \{(u, v) : 0 < u < 2\pi, 0 < v < 2\pi\}$. Consider a curve in M of the form

$$\boldsymbol{\gamma}(t) = \mathbf{x}(u(t), v(t)), \quad t \in I \subset \mathbb{R},$$

with $(u(t), v(t))$ a regular parametrised curve in U .

- (a) A basis for the tangent space $T_\gamma M$ at each point along the curve is given by $\{\mathbf{x}_u, \mathbf{x}_v\}$ evaluated on the curve. Give an expression for this basis on the above chart for the torus. Find an *orthonormal* basis $\{\boldsymbol{\xi}_1(t), \boldsymbol{\xi}_2(t)\}$ for the tangent space. [4]

(b) Let

$$\dot{\boldsymbol{\xi}}_1 = c_1(t)\boldsymbol{\xi}_1(t) + c_2(t)\boldsymbol{\xi}_2(t) + \nu_1(t)\mathbf{n}(t) \quad \text{and} \quad \dot{\boldsymbol{\xi}}_2 = \omega(t)\boldsymbol{\xi}_1(t) + c_3(t)\boldsymbol{\xi}_2(t) + \nu_2(t)\mathbf{n}(t),$$

where $\mathbf{n}(t)$ is the normal vector at each point along the curve. Show that $c_1 = c_3 = 0$ and $c_2 = -\omega(t)$ and find an explicit expression for $\omega(t)$ for a path on the torus. It is not necessary to find expressions for $\nu_1(t)$ or $\nu_2(t)$. [7]

- (c) A *vectorfield* $\mathbf{w}(t)$ along the curve in M can be expressed in the form

$$\mathbf{w}(t) = w_1(t)\boldsymbol{\xi}_1(t) + w_2(t)\boldsymbol{\xi}_2(t),$$

where $w_1(t)$ and $w_2(t)$ are real-valued functions. Give conditions for the vectorfield $\mathbf{w}(t)$ to be *parallel*. [3]

- (d) Find the differential equations that $w_1(t)$ and $w_2(t)$ must satisfy for a vectorfield $\mathbf{w}(t)$ to be parallel on M . [5]

- (e) Suppose $0 < t < \pi$ and take $w_1(0) = 1$ and $w_2(0) = 0$. Find the coefficients $(w_1(t), w_2(t))$ for a parallel vectorfield on M along the path $u(t) = u_0$ with $u_0 \in (0, \pi)$ and $v(t) = t$. [6]