

# The University of Nottingham

SCHOOL OF COMPUTER SCIENCE AND INFORMATION  
TECHNOLOGY

A LEVEL B MODULE, AUTUMN SEMESTER 2002-2003

## ALGORITHMS AND DATA STRUCTURES

Time allowed TWO Hours

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*Candidates must NOT start writing their answers until told to do so*

***Answer QUESTION ONE and THREE other questions***

*No calculators are permitted in this examination.*

*Dictionaries are not allowed with one exception. Those whose first language is not English may use a dictionary to translate between that language and English provided that neither language is the subject of this examination. No electronic devices capable of storing and retrieving text may be used.*

***DO NOT turn your examination paper over until instructed to do so.***

### ***Additional Material:***

1. Description of the Vector class

1. This multiple choice question is compulsory. In each part, select one answer. For parts (a) to (h), you get 3 points if you select the right answer and 0 if you don't. For part (i) you get one point if you select the right answer.

(a) An algorithm's memory usage is described by the following function:  $s(n) = 10n + 2n \log_2 n$ . What is the algorithm's space complexity (choose the tightest upper bound): (3)

- i.  $O(1)$
- ii.  $O(\log n)$
- iii.  $O(n)$
- iv.  $O(n \log n)$
- v.  $O(n^2)$

(b) Which one of the following is an invariant of the loop:

```
int indexGreatest = 0;
for (int i = 1; i < array.length; i++){
    if (array[i] > array[indexGreatest]) indexGreatest = i;
}
```

 (3)

- i. for all  $j$ , if  $0 \leq j \leq i$ , then  $\text{array}[j] \leq \text{array}[\text{indexGreatest}]$
- ii. for all  $j$ , if  $0 \leq j < i$ , then  $\text{array}[j] \leq \text{array}[\text{indexGreatest}]$
- iii. for all  $j$ , if  $0 \leq j < i$ , then  $\text{array}[j] < \text{array}[\text{indexGreatest}]$
- iv. for all  $j$ , if  $0 \leq j \leq i$ , then  $\text{array}[j] < \text{array}[\text{indexGreatest}]$
- v.  $\text{indexGreatest} = 0$

(c) Suppose that the running time of an algorithm has a linear growth rate. On inputs of size 1000 it runs in 20 ms. What would be your estimate of its running time on inputs of size 10000? (3)

- i. 40 ms
- ii. 400 ms
- iii. 4000 ms
- iv. 200 ms
- v. 2000 ms

*Question continued overleaf*

- (d) Which of the code fragments below has the following loop invariant:  $\text{result} = n^i$  (3)

```
i. int power(int n, int k){
    int result = n;
    for (int i = 1; i < k; i++){
        result = result * n;
    }
}

ii. int power(int n, int k){
    int result = 1;
    for (int i = 1; i < k; i++){
        result = result * n;
    }
}

iii. int power(int n, int k){
    int result = n;
    for (int i = 1; i < k; i++){
        result = result * result;
    }
}

iv. int power(int n, int k){
    int result = n;
    for (int i = 0; i < k; i++){
        result = result * n;
    }
}

v. int power(int n, int k){
    int result = n;
    for (int i = 1; i < k; i++){
        result = n * n;
    }
}
```

*Question continued overleaf*

- (e) What is the tightest upper bound on the growth rate of running time for the following algorithm: (3)

```
int algorithm(int n){
    int k = 0;
    while (n > 1) {
        n = n/2; k++;
    }
    return k;
}
```

- i.  $O(1)$
  - ii.  $O(\log n)$
  - iii.  $O(n)$
  - iv.  $O(n \log n)$
  - v.  $O(n^2)$
- (f) Due to hash collisions, hash tables in Java use buckets to store multiple items with keys which hash to the same value. To find an item with a given key in the hash table, the key is hashed (which is a constant time operation), the right bucket accessed (in constant time) and then the bucket has to be searched sequentially. What is the worst case performance for search: (3)
- i. constant time
  - ii. logarithmic in the number of buckets
  - iii. logarithmic in the number of items in the table
  - iv. linear in the number of buckets
  - v. linear in the number of items in the table
- (g) Which data structure has reliably efficient (logarithmic) performance for search, insertion and deletion: (3)
- i. unordered list
  - ii. ordered list
  - iii. ordered array
  - iv. binary search tree
  - v. balanced binary search tree

*Question continued overleaf*

- (h) One of the sorting algorithms below works significantly faster if the input data is already sorted or almost sorted. Which one is it? (3)
- i. bubble sort
  - ii. selection sort
  - iii. insertion sort
  - iv. merge sort
  - v. quick sort
- (i) Binary search works on unordered arrays: (1)
- i. yes
  - ii. no

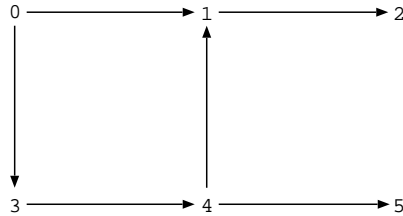
2. (a) Using the following auxiliary Node class (15)

```
class Node {
    Object value;
    Node next;
    Node(Object v, Node n) {
        this.value = v;
        this.next = n; }}
```

write a Java implementation of a simple single ended, single linked List class with the following methods:

- `public List() // constructor`  
Postcondition: creates an empty list
  - `public void insert(Object o)`  
Postcondition: inserts o at the head of the list
  - `public void remove()`  
Postcondition: removes the head of the list. If the list is empty, does nothing.
  - `public boolean search(Object o)`  
Postcondition: returns true if o is in the list, false otherwise.
  - `public Object head()`  
Postcondition: returns the object stored at the head of the list, without updating the list; if the list is empty, returns null.
- (b) Using only the List class methods defined above, give an implementation of the following Stack ADT: (10)
- `public Stack() // constructor`  
Postcondition: creates an empty stack
  - `public void push(Object o)`  
Postcondition: pushes o on top of the stack
  - `public Object pop()`  
Postcondition: pops the stack and returns the value on top. If the stack is empty, returns null.
  - `public Object peek()`  
Postcondition: returns the Object on top without updating the stack; if the stack is empty, returns null.

3. (a) How would you represent a directed graph as an adjacency matrix? Illustrate your answer using the following example: (5)



- (b) Describe in English an algorithm to check whether a graph represented as an adjacency matrix contains a cycle (a path from some vertex to itself). Explain why this algorithm is correct. (5)
- (c) Based on the algorithm you described above, give a Java implementation of the following method: (15)

```
boolean hasCycles(int [] [] matrix, int n)
```

Precondition: `matrix` is a two-dimensional array containing only 0s and 1s, both dimensions are of size `n`.

Postcondition: the method returns `true` if `matrix` corresponds to a cyclic graph, and `false` otherwise.

You may change the contents of the `matrix`. Your solution may make use of additional methods which the `hasCycles()` method calls.

4. (a) What is a perfectly balanced binary tree? (3)
- (b) Prove by induction that level  $i$  in a perfectly balanced binary tree contains  $2^i$  nodes, assuming that the first level (the root) is level 0. (5)
- (c) Prove by induction that a perfectly balanced binary tree with  $k$  levels has  $2^k - 1$  nodes. (10)
- (d) Give pseudocode for a method to search for an item given a key in a binary search tree. Show that in a perfectly balanced binary search tree, time complexity of search in the worst case is  $O(\log_2 n)$ , where  $n$  is the number of nodes in the tree. (7)

5. (a) What is a heap data structure? (5)
- (b) Describe how insertion and deletion in heaps works and why it makes them suitable for implementing priority queues. (5)
- (c) Write a Java class Heap which uses a Vector to store the contents of a heap. Vector class API description is enclosed. The class should contain a method to insert a new item in the heap (`void insert(Item i)`) and a method which removes the root and returns it (`Item remove()`). Assume that items stored in the Heap are instances of the class (15)

```
class Item {
    Object value;
    int key;

    public Item(Object o, int i) {
        this.value = o;
        this.key = i;
    }

    public int key() {
        return key;
    }

    public Object value() {
        return value;
    }
}
```

and the Heap is ordered on the `key()` values of the items.

6. Write a clear and well structured essay on the ways in which the differences between main memory and peripheral storage affect the design of algorithms and data structures. (25)