

# THE UNIVERSITY of Liverpool 

## MAY EXAMINATIONS 2007

Bachelor of Arts: Year 2<br>Bachelor of Science: Year 2<br>Bachelor of Science: Year 3<br>Master of Mathematics: Year 2<br>Master of Mathematics: Year 3<br>Master of Physics: Year 2

CLASSICAL MECHANICS

TIME ALLOWED : Two Hours and a Half

## INSTRUCTIONS TO CANDIDATES

You may attempt all questions. All answers to Section A and the best THREE questions from Section B will be taken into account. Section A carries $55 \%$ of the available marks. The marks shown against the sections indicate their relative weights.

## THE UNIVERSITY <br> of Liverpool <br> SECTION A

1. A particle moves in space in accordance with the equation

$$
x^{3}+\cos (2 y)-3 z=A t
$$

where $A$ is a constant.
Given that, at time $t=0$, the position vector $\mathbf{r}$ and the velocity $\mathbf{v}$ of the particle are

$$
\mathbf{r}=B \mathbf{i}+3 \mathbf{k} \quad \text { and } \quad \mathbf{v}=-\mathbf{i}+\mathbf{j}-2 \mathbf{k},
$$

where $B$ is a constant, find $A$ and $B$.
2. A particle of mass $m$ is dropped from the origin $O$ with no initial speed in a medium with resistance. The coordinate axis $x$ is chosen to be vertically downwards as shown in the Figure. The magnitude of the resisting force is assumed to be $F_{\text {res }}=m g \lambda v$, where $g$ is the gravitational acceleration and $\lambda$ is a constant. Show that the speed of the particle is given by

$$
v(t)=v_{l}\left(1-\mathrm{e}^{-g t / v_{l}}\right),
$$

clarifying the notation for $v_{l}$, and hence find its displacement $x(t)$.

[10 marks]
3. A rigid uniform lamina lies in the $x y$-plane and is bounded by the lines $x=2 a, y=x / 2+a$ and the coordinate axes $x$ and $y$, as shown in the Figure.
Find the coordinates of the centre of mass of this lamina.
The lamina is now rotated through $2 \pi$ about the line $y=-2 a / 9$. Show, by the use of the Theorem of Pappus-Guldin or otherwise, that the volume swept out is given by $6 \pi a^{3}$.

[9 marks]

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4. (a) The vector $\boldsymbol{\omega}$ is said to be the angular velocity vector of a rigid body, if $\frac{d \mathbf{a}}{d t}=\boldsymbol{\omega} \times \mathbf{a}$ holds true for every vector a embedded into the body. Prove that the vector $\boldsymbol{\omega}$ defined in this way is uniquely determined.
[3 marks]
(b) A rigid uniform circular cone is attached at its vertex to a stationary fixed pivot at the origin $O$. The motion of the cone about $O$ is constrained so that its axis of symmetry $O Z$ always remains in the $y z$-plane. At time $t, \theta$ is the angle between the vertically upwards $y$-axis and the cone's axis of symmetry $O Z$, and $\phi$ is the angle denoting the rotation about the $O Z$-axis.


Assuming that $O x y z$ form a right-handed frame, show that the angular velocity of the cone at time $t$ is given by

$$
\boldsymbol{\omega}=\dot{\theta} \mathbf{i}+\dot{\phi} \cos \theta \mathbf{j}+\dot{\phi} \sin \theta \mathbf{k}
$$

where $\mathbf{i}, \mathbf{j}, \mathbf{k}$ denote unit vectors along the axes $x, y, z$ respectively.
[8 marks]
5. A rigid rectangular lamina of sides $a$ and $3 a$ with centre $C$ moves in the $x y$-plane at all times, as shown in the Figure. The velocities of the two corners $A$ and $B$ of the lamina are given to be $\mathbf{v}_{A}$ and $\mathbf{v}_{B}$ at time $t$, respectively. Find the velocity of the centre point $C$, i.e. $\mathbf{v}_{C}$, in terms of $\mathbf{v}_{A}$ and $\mathbf{v}_{B}$.
Also show that the magnitude of the angular velocity of the lamina is given by $\left|\mathbf{v}_{A}-\mathbf{v}_{B}\right| /(\sqrt{10} a)$.

[9 marks]

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6. A thin solid rod of mass $M$, length $l$ and of uniform cross section is being lifted from the ground to a vertical position by the use of a thrust applied at one end $A$ of the rod, as shown in the Figure. The magnitude of the thrust is $3 M g / 2$ and this thrust is in the vertically upwards $y$-direction. The other end of the rod is fixed at the point $O$, the origin of the $x y$-plane and the rod remains in the
 $x y$-plane at all times. The $z$-axis is oriented out of the page, so that $O x y z$ form a righthanded frame.

Given that the moment of inertia of the rod about the $z$-axis is $I$ and that, at time $t$, the rod makes an angle $\phi$ with the horizontal $x$-axis, using the equation for rotational motion about the origin $O$, show that

$$
M g l \cos \phi=I \ddot{\phi} .
$$

Now, multiplying the above equation by $\dot{\phi}$, integrating with respect to time $t$ and using the condition that at $t=0$ the rod is at rest horizontally, show that the magnitude of its angular velocity is $\sqrt{2 M g l / I}$ when the rod is vertically upwards.

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 <br> <br> SECTION B}
7. (a) Using the Figure on the right, find the unit vector $\mathbf{e}_{r}(t)$ in the radial direction and $\mathbf{e}_{\phi}(t)$ in the tangential direction, where $t$ stands for time, in terms of the unit vectors $\mathbf{i}, \mathbf{j}$ along the coordinate axes $x, y$ respectively.
Hence, deduce that

$$
\dot{\mathbf{e}}_{r}=\dot{\phi} \mathbf{e}_{\phi}, \quad \dot{\mathbf{e}}_{\phi}=-\dot{\phi} \mathbf{e}_{r},
$$


and use these derivatives and the position vector

$$
\mathbf{r}(t)=r(t) \mathbf{e}_{r}(t)
$$

to find the components of the velocity vector $\mathbf{v}=\frac{d \mathbf{r}}{d t}$.
[7 marks]
(b) By differentiating the velocity vector $\mathbf{v}$ with respect to time, the acceleration vector in polar coordinates can be found as

$$
\mathbf{a}=\left(\ddot{r}-r \dot{\phi}^{2}\right) \mathbf{e}_{r}+(2 \dot{r} \dot{\phi}+r \ddot{\phi}) \mathbf{e}_{\phi} .
$$

Consider a particle of mass $m$ moving on the circle of centre $(R, 0)$ and radius $R$ as shown in the Figure on the right. Given the equation of the circle is $r=2 R \cos \phi$, where $r$ denotes the distance to the circle from the origin and
 $\phi$ is the angle between the horizontal $x$-axis and $r$, and that $a_{\phi}=0$ throughout the motion of the particle, show that

$$
\dot{\phi}=\frac{C}{r^{2}},
$$

where $C$ is an arbitrary constant and hence find $F_{r}$, the only nonzero component of the force, acting on the particle at time $t$.

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8. (a) A uniform solid paraboloid of mass $M$ and of height $2 a$ is placed symmetrically about the $z$-axis. In terms of cyclindrical polar coordinates: $x=r \cos \phi, y=r \sin \phi, z=z$, the equation of the curved surface of this paraboloid is given by $z=2 r^{2} / a$, where $0 \leq z \leq 2 a, 0 \leq \phi \leq 2 \pi$.
Identify the principal axes of inertia for this paraboloid at the origin $O$.
Now, show that the volume of the paraboloid is $\pi a^{3}$ and hence find the moment of inertia of the paraboloid about the $z$-axis, i.e. $I_{O z}$.

[8 marks]
(b) The Figure shows a rigid uniform lamina of mass $M$ in the $x y$-plane in the shape of a quarter of a circle of radius $a$ in the second quadrant. $O x, O y$ are the body axes and the axis $O z$ is perpendicular to the $x y$-plane, forming a right handed frame.
Obtain the Cartesian equations of the princi-
 pal axes of inertia at the origin $O$ for the lamina by considering its symmetry properties.
Given that the inertia matrix at $O$ with respect to $O x y z$ is

$$
\frac{M a^{2}}{4 \pi}\left(\begin{array}{ccc}
\pi & 2 & 0 \\
2 & \pi & 0 \\
0 & 0 & 2 \pi
\end{array}\right)
$$

write down column matrices representing vectors parallel to the principal axes you found and hence, obtain the principal moment of inertia corresponding to each principal axis.
[7 marks]

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9. A man runs forward, balancing one end $C$ of a long rigid rod of mass $M$ and of uniform thickness in his hands. The end $C$ moves parallel to the horizontal $x$-axis with constant acceleration of magnitude $g \cot \alpha, 0<\alpha<\pi / 2$. The centre of mass $G$ of the rod is at a distance $a$ away from $C$, and at time $t$, the rod makes an acute angle $\phi$ with the horizontal, as shown in the Figure. The motion of the rod is at all times in the $x y$-plane, where $y$-axis is
 vertically upwards. It is assumed that $O x y z$ form a right-handed frame.
Given that the rod has a principal axis of inertia through $G$ perpendicular to the $x y$-plane with moment of inertia $M a^{2} / 3$ about this axis, use the theorem of parallel axis to find its moment of inertia about a parallel axis through $C$.

Hence, using the equation for the rotational motion of the rod about the point $C$, show that

$$
4 a \sin \alpha \ddot{\phi}=3 g \sin (\phi-\alpha) .
$$

Let $\phi(t)=\alpha+\varepsilon(t)$, where $|\varepsilon|$ is small. Substitute this into the above equation of motion and obtain an approximate solution to the resulting differential equation. Hence verify that the above equilibrium state is dynamically unstable.

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10. The Figure shows a rigid uniform disc of centre $C$ and radius $a$, rolling inside a fixed disc of centre $O$ and radius $3 a$. The motion is planar at all times and two unit vectors $\mathbf{m}$ and $\mathbf{n}$ are introduced along the radial and tangential directions for convenience. At time $t, \theta$ is the angle between the upward vertical $y$-axis and $C P$, where $P$ is a point on the inner circle's rim, and $\phi$ is the angle between the $y$-axis and $O B$, where $B$ is the instantaneous point of contact of the two discs, as shown in the
 Figure.
Find the velocity of the centre point $C$ in terms of $a$ and $\phi$, and specify its direction.
Assuming that there is no slipping between the discs, show that $2 \dot{\phi}=\dot{\theta}$ and hence apply the law of conservation of energy to further show that

$$
\begin{equation*}
3 a \dot{\phi}^{2}-2 g \cos \phi=\text { const. } \tag{15marks}
\end{equation*}
$$

11. At time $t$, the components of the angular velocity of a uniform rigid body along its principal axes of inertia $G X, G Y, G Z$ at its centre of mass $G$, are $\omega_{1}(t), \omega_{2}(t)$ and $\omega_{3}(t)$ respectively. The corresponding principal moments of inertia at $G$ are $I, 2 I$ and $I$ respectively.
If all the external forces on the body act at $G$, show that the angular momentum of the body at $G$ is constant.
Hence use the Euler's form to show that the Euler equations for the three-dimensional motion of the body can be written as

$$
\dot{\omega}_{1}=s \omega_{3}, \quad \omega_{2}=s, \quad \dot{\omega}_{3}=-s \omega_{1}
$$

where $s$ is a constant. Hence, find the differential equations $\omega_{1}$ and $\omega_{3}$ satisfy and solve them.
Now, consider the case when there exists a force of constant magnitude $T$ on the $Y Z$-plane acting at a point $P$ on $G Z$, a distance $a$ away from $G$, making a constant angle $\phi$ with the $G Z$ axis, as shown in the Figure. Show that the component of the angular velocity $\omega_{3}$ can now be found as

$w_{3}(t)=C_{1} \cos \left(s t+C_{2}\right)+\frac{a T}{s I} \sin \phi, \quad C_{1}, C_{2}=$ const.
[15 marks]

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## FORMULAE SHEET

Note: In the formulae listed below, $C$ is a body point whereas $O$ is a point fixed in space, and dot denotes the time derivative.
Centre of mass: $\quad \mathbf{r}_{G}=\frac{1}{V} \int_{V} \mathbf{r} d V$
Inertia matrix: $\quad \frac{M}{V} \int_{V}\left(\begin{array}{ccc}y^{2}+z^{2} & -x y & -x z \\ -x y & x^{2}+z^{2} & -y z \\ -x z & -y z & x^{2}+y^{2}\end{array}\right) d V$
Angular velocity: $\mathbf{v}_{P}=\mathbf{v}_{C}+\boldsymbol{\omega} \times \mathbf{C P}$
Angular momentum: $\quad \mathbf{L}_{C}=I_{1} \omega_{1} \mathbf{I}+I_{2} \omega_{2} \mathbf{J}+I_{3} \omega_{3} \mathbf{K}$

$$
\mathbf{L}_{O}=M\left(\mathbf{r}_{G} \times \mathbf{v}_{G}\right)+\mathbf{L}_{G}
$$

Kinetic energy: $\quad T_{C}=\frac{1}{2}\left(I_{1} \omega_{1}^{2}+I_{2} \omega_{2}^{2}+I_{3} \omega_{3}^{2}\right)$

$$
T_{O}=\frac{1}{2} M\left|\mathbf{v}_{G}\right|^{2}+T_{G}
$$

Equations of motion: $\quad \sum_{i} \mathbf{F}_{i}=M \dot{\mathbf{v}}_{G}$

$$
\begin{aligned}
\sum_{i} \mathbf{C P}_{i} \times \mathbf{F}_{i} & =M\left(\mathbf{C G} \times \dot{\mathbf{v}}_{C}\right)+\dot{\mathbf{L}}_{C} \\
\sum_{i} \mathbf{O P}_{i} \times \mathbf{F}_{i} & =\dot{\mathbf{L}}_{O}
\end{aligned}
$$

Euler form: $\quad \dot{\mathbf{L}}_{C}=\left[I_{1} \dot{\omega}_{1}-\left(I_{2}-I_{3}\right) \omega_{2} \omega_{3}\right] \mathbf{I}$

$$
\begin{aligned}
& +\left[I_{2} \dot{\omega}_{2}-\left(I_{3}-I_{1}\right) \omega_{3} \omega_{1}\right] \mathbf{J} \\
& +\left[I_{3} \dot{\omega}_{3}-\left(I_{1}-I_{2}\right) \omega_{1} \omega_{2}\right] \mathbf{K}
\end{aligned}
$$

