### MATH-5031M01

This question paper consists of 5 printed pages, each of which is identified by the reference MATH-5031M01

Only approved basic scientific calculators may be used.

# © UNIVERSITY OF LEEDS

Examination for the Module MATH-5031M

(January 2006)

### Differential Geometry 2

Time allowed: 3 hours

Answer a maximum of **four** questions from Section A and a maximum of **two** questions from Section B. All questions carry equal marks.

Throughout this paper, by 'surface' we shall mean 'smooth regular embedded m-surface in  $\mathbb{R}^n$  for some positive integers m and n'.

## SECTION A

1. (a) Let  $\gamma : [0, b] \to \mathbb{R}^2$  be a regularly parametrized curve. What is meant by saying that  $\gamma$  is closed? What is meant by the total curvature of a regularly parametrized closed curve?

Let  $\gamma_0 : [0, b_0] \to \mathbb{R}^2$  and  $\gamma_1 : [0, b_1] \to \mathbb{R}^2$  be regularly parametrized closed curves. What is meant by a regular homotopy from  $\gamma_0$  to  $\gamma_1$ ? State the Whitney-Graustein Theorem.

(b) Let  $\gamma(t) = (4\sin 2t, 4\cos 2t)$   $(t \in [0, 5\pi])$ . Calculate the total curvature of  $\gamma$ .

(c) By finding a suitable regular homotopy and quoting the Whitney–Graustein Theorem, or otherwise, find the total curvature of the closed curve  $\alpha : [0, 5\pi] \to \mathbb{R}^2$  given by

$$\alpha(t) = (4\sin 2t - 2\sin t, 4\cos 2t + 2\cos t).$$

Show that

$$H(u,t) = (4u\sin 2t - 2\sin t, 4u\cos 2t + 2\cos t) \qquad (u \in [0,1], t \in [0,5\pi])$$

does not define a regular homotopy.

2. (a) Let  $\varphi : M \to M'$  be a smooth map between surfaces, and let  $p \in M$ . Define what is meant by the differential  $d\varphi_p: T_pM \to T_{\varphi(p)}M'$  of  $\varphi$  at p. Let

$$X: U \to M$$
,  $\mathbf{u} = (u_1, \dots, u_m) \mapsto X(\mathbf{u})$ 

be a local parametrization of M with  $X(\mathbf{0}) = p$ . Write  $\hat{\varphi} = \varphi \circ X$  and  $\epsilon_i = \partial X / \partial u_i$  $(i = 1, \ldots, m)$ . Show that

$$\mathrm{d}\varphi_p(\epsilon_i) = \frac{\partial \hat{\varphi}}{\partial u_i}(\mathbf{0}) \qquad (i = 1, \dots, m).$$

Deduce that, if  $\mathbf{v} \in T_p M$  is given by  $\mathbf{v} = \sum_{i=1}^m v_i \epsilon_i$ , then

$$\mathrm{d}\varphi_p(\mathbf{v}) = \sum_{i=1}^m v_i \,\mathrm{d}\varphi_p(\epsilon_i)\,.$$

(b) Let  $f: M \to M'$  be a smooth map between surfaces. Define what is meant by f is a *local isometry*.

Show that, if f is a local isometry then,

(\*) for any smooth curve  $\alpha : [a, b] \to M$  defined on a closed interval [a, b], the length of  $f \circ \alpha$  is equal to the length of  $\alpha$ .

Show conversely that, if  $f: M \to M'$  is a smooth map having the property (\*), then it is a local isometry.

**3.** (a) Let  $f : \mathbb{R}^3 \to \mathbb{R}$  be the smooth function  $f(x_1, x_2, x_3) = x_1^2 + x_2^2 + x_2^2$ . For r > 0, set  $S^2(r) = f^{-1}(r)$ . Show that f is regular on  $S^2(r)$ , so that  $S^2(r)$  is a 2-surface. Without parametrizing  $S^2(r)$ , show that its shape operator S at any point  $p \in S^2(r)$  is given by

$$S(\mathbf{v}) = c \, \mathbf{v} \qquad \left(\mathbf{v} \in T_p S^2(r)\right)$$

for some constant c to be determined.

(b) Let M be a surface and let  $\gamma : I \to M$  be a smooth curve defined on an interval I. Say what is meant by  $\gamma$  is a geodesic on M. Show that the speed  $|\gamma'(t)|$   $(t \in I)$  of a geodesic is constant.

(c) Suppose that  $\gamma: I \to S^2(r)$  is a geodesic of unit speed. Show that it is a plane curve of constant curvature 1/r; deduce that its track lies on a great circle of  $S^2(r)$ .

Suppose, instead, that  $\gamma : I \to S^2(r)$  is a smooth curve of unit speed whose principal normal makes a constant angle with a unit normal of  $S^2(r)$ . Show that the track of  $\gamma$  lies on a circle and give the radius of that circle.

[You may assume that the track of a unit speed plane curve of constant curvature 1/r lies on a circle of radius r.] 4. (a) Let  $f: M \to M'$  be a smooth map between 2-surfaces. Say what is meant by f is conformal with scale factor  $\lambda$ . Show that a smooth map  $f: M \to M'$  is conformal with scale factor  $\lambda$  if and only if

$$\mathrm{d}f_p(\mathbf{v})\cdot\mathrm{d}f_p(\mathbf{w}) = \lambda(p)^2 \,\mathbf{v}\cdot\mathbf{w} \qquad (p \in M, \ \mathbf{v}, \mathbf{w} \in T_p M) \,.$$

Give a formula for the angle between two non-zero vectors, and show that a smooth map  $f: M \to M'$  is conformal if and only if it preserves angles in the sense that, for all  $p \in M$  and all non-zero  $\mathbf{v}, \mathbf{w} \in T_p M$ , the vectors  $df_p(\mathbf{v})$  and  $df_p(\mathbf{w})$  are non-zero and the angle between them is equal to the angle between  $\mathbf{v}$  and  $\mathbf{w}$ .

(b) Let 
$$S^2 = \{(x, y, z) : x^2 + y^2 + z^2 = 1\}$$
 and

$$E^{2} = \left\{ (x, y, z) : \frac{x^{2} + y^{2}}{a^{2}} + \frac{z^{2}}{b^{2}} = 1 \right\}$$

where a and b are positive constants. Define a smooth map  $f: S^2 \to E^2$  by

$$f(x, y, z) = (ax, ay, bz).$$

Show that f is conformal if and only if a = b. Determine the scale factor of f in this case.

5. (a) Give a formula which defines a local isometry from the plane  $\mathbb{R}^2$  to the unit circular cylinder  $C = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 = 1\}$ . [You need not show that this is a local isometry.]

(b) Let M be a 2-surface in  $\mathbb{R}^3$ . What is meant by saying that a property is (A) *intrinsic*, (B) *extrinsic*. Show that the following properties are extrinsic: (i) principal curvatures; (ii) mean curvature; (iii) distance between pairs of points [You may quote the values of the principal curvatures of  $\mathbb{R}^2$  in  $\mathbb{R}^3$  and of C in  $\mathbb{R}^3$  without proof.] State the *Theorema Egregium* of Gauss.

(c) Let M be a closed 2-surface. Explain briefly what is meant by the (i) total curvature of M, (ii) Euler characteristic of M. [You need not define what is meant by a triangulation or show that the Euler characteristic is well defined.] State the Gauss-Bonnet Theorem.

Let M be a closed 2-surface with Euler characteristic 0 and Gauss curvature K satisfying  $K \leq 0$  at all points. Show that K is identically zero.

### SECTION B

6. (a) Prove that, for any nonnegative real numbers a and b,

$$\sqrt{ab} \le \frac{1}{2}(a+b) \,.$$

Prove that, for any four real numbers  $a_1, a_2, b_1, b_2$ ,

$$\left(\sum_{i=1}^2 a_i b_i\right)^2 \le \left(\sum_{i=1}^2 a_i^2\right) \left(\sum_{i=1}^2 b_i^2\right).$$

(b) Let  $C: s \mapsto \mathbf{x}(s) = (x_1(s), x_2(s))$   $(s \in [0, L])$  be a positively oriented unit speed simple closed curve in the plane of length L which encloses an area A. Describe how to construct a circle  $\overline{C}: s \mapsto \overline{\mathbf{x}}(s) = (\overline{x}_1(s), \overline{x}_2(s))$   $(s \in [0, L])$  with  $\overline{x}_1(s) = x_1(s)$   $(s \in [0, L])$ . Show that

$$A + \pi r^2 \le Lr$$
 .

where r is the radius of the circle. Deduce the isoperimetric inequality:

$$4\pi A \le L^2.$$

- 7. Let M be a 2-surface in  $\mathbb{R}^3$  and let  $X : U \to M$ ,  $(u, v) \mapsto X(u, v)$  be a local parametrization of M. As usual, write  $\epsilon_1 = \partial X/\partial u$  and  $\epsilon_2 = \partial X/\partial v$ ,  $E = \epsilon_1 \cdot \epsilon_1$ ,  $F = \epsilon_1 \cdot \epsilon_2 = \epsilon_2 \cdot \epsilon_1$ ,  $G = \epsilon_2 \cdot \epsilon_2$ ,  $L = S(\epsilon_1) \cdot \epsilon_1$ ,  $M = S(\epsilon_1) \cdot \epsilon_2 = S(\epsilon_2) \cdot \epsilon_1$ ,  $N = S(\epsilon_2) \cdot \epsilon_2$ , where S is the shape operator of M at p.
  - (a) Show that the Gauss curvature K of M at a point in the image of X is given by

$$K = \frac{LN - M^2}{EG - F^2} \,.$$

(b) Write

$$X_{uu} = \Gamma_{11}^{1} X_{u} + \Gamma_{11}^{2} X_{v} + L \mathbf{N}$$
  

$$X_{uv} = \Gamma_{12}^{1} X_{u} + \Gamma_{12}^{2} X_{v} + M \mathbf{N}$$
  

$$X_{vu} = \Gamma_{21}^{1} X_{u} + \Gamma_{21}^{2} X_{v} + M \mathbf{N}$$
  

$$X_{vv} = \Gamma_{22}^{1} X_{u} + \Gamma_{22}^{2} X_{v} + N \mathbf{N}$$

Suppose that F is identically zero. Show that

$$\Gamma_{11}^1 = \frac{1}{2} \frac{E_u}{E} \,,$$

and find similar formulae for the other  $\Gamma_{ij}^k$  (i, j, k = 1, 2).

Show that  $LN - M^2$  is expressible in terms of these functions and E, G and their derivatives. Deduce that the Gauss curvature K is expressible in terms of E, G and their derivatives. [You need not find the exact expression for  $LN - M^2$  or for K.] 8. (a) Let M be a surface. Define what is meant by a (smooth) Riemannian metric on M.

(b) Let  $\mathbb{R}^2_+ = \{(x, y) \in \mathbb{R}^2 : y > 0\}$  and let g be the hyperbolic metric on  $\mathbb{R}^2_+$  given at a point p = (x, y) of  $\mathbb{R}^2_+$  by

$$g_p(\mathbf{v},\mathbf{w}) = rac{1}{y^2} \, \mathbf{v} \cdot \mathbf{w}$$
 .

Show that the following bijective smooth maps of  $(\mathbb{R}^2_+, g)$  are isometries:

(i) 
$$\psi(x,y) = (x+\lambda, y)$$
  $(\lambda \in \mathbb{R}),$   
(ii)  $\psi(x,y) = (\lambda x, \lambda y)$   $(\lambda \in \mathbb{R}, \lambda \neq 0),$   
(iii)  $\psi(x,y) = (-x, y),$   
(iv)  $\psi(x,y) = \left(\frac{x}{x^2+y^2}, \frac{y}{x^2+y^2}\right).$ 

[You do not need to show that these maps are smooth and bijective, and you may assume that a smooth bijective map  $\psi : \mathbb{R}^2_+ \to \mathbb{R}^2_+$  is an isometry if and only if, for each  $p \in \mathbb{R}^2_+$ , there is a basis  $\{e_1, e_2\}$  of  $T_p \mathbb{R}^2_+$  such that  $g_{\psi(p)}(\mathrm{d}\psi_p(e_i), \mathrm{d}\psi_p(e_j)) = g_p(e_i, e_j)$  (i = 1, 2).]

(c) Find an isometry of  $(\mathbb{R}^2_+, g)$  which preserves the semicircle of centre (0, 0), radius 3, but is not the identity map. Hence find  $a \in (0, \infty)$  such that the distance from (0, 1) to (0, 2) is equal to the distance of (0, a) to (0, 9) without calculating these distances.

### END