Generative

Bayesian classification



2 Bayesian logistic regression & Laplace approximation



Likelihood model

- Two class (binary) classification, discriminative approach: need model for $p(C_1|\mathbf{x}, \mathbf{w}) = 1 - p(C_2|\mathbf{x}, \mathbf{w})$
- Keep this 'almost' linear in parameter vector w:

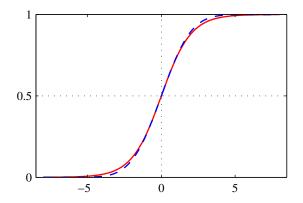
$$p(\mathcal{C}_1|\mathbf{x}, \mathbf{w}) = \sigma(\mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x})), \quad \sigma(a) = 1/(1 + e^{-a})$$

- $\bullet~\sigma(a) = {\rm logistic~sigmoid,~`squashing'~or~`activation'~function}$
- Inverse: logit $a = \ln(\sigma/(1-\sigma))$, 'link' function
- Model known as 'logistic regression' (but it's classification!)
- Other choices for $\sigma(a)$ are possible, e.g. inverse probit

$$\sigma(a) = \int_{-\infty}^{a} \mathcal{N}(\theta|0, 1) d\theta$$

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Activation functions



Red: logistic sigmoid; blue: inverse probit

Likelihood model

• Represent class \mathcal{C}_1 as t=1, \mathcal{C}_2 as t=0, then

$$p(\mathbf{t}|\mathbf{w}) = \prod_{n=1}^{N} y_n^{t_n} (1-y_n)^{1-t_n}, \quad y_n = p(\mathcal{C}_1|\mathbf{x}_n, \mathbf{w}) = \sigma(\mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}_n))$$

• Maximum likelihood minimizes cross-entropy error function

$$E(\mathbf{w}) = -\ln p(\mathbf{t}|\mathbf{w}) = -\sum_{n} [t_n \ln y_n + (1 - t_n) \ln(1 - y_n)]$$

• Gradient:

$$\nabla E(\mathbf{w}) = \sum_{n} (y_n - t_n) \boldsymbol{\phi}(\mathbf{x}_n) = \boldsymbol{\Phi}^{\mathrm{T}}(\mathbf{y} - \mathbf{t})$$

5/18

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Likelihood model (2)

• Hessian of E:

$$\nabla \nabla E(\mathbf{w}) = \sum_{n} y_n (1 - y_n) \boldsymbol{\phi}(\mathbf{x}_n) \boldsymbol{\phi}(\mathbf{x}_n)^{\mathrm{T}} = \boldsymbol{\Phi}^{\mathrm{T}} \mathbf{R} \boldsymbol{\Phi}$$

with $\mathbf{R} = \text{diagonal matrix}, R_{nn} = y_n(1 - y_n)$

- Positive definite $\Rightarrow E$ is convex, only has a single minimum
- So $p(\mathbf{t}|\mathbf{w})$ is log-concave, only has a single maximum
- Can be found efficiently numerically (iterative reweighted least squares)

Generalizations

• Allowing labelling noise:

$$p(\mathcal{C}_1 | \mathbf{x}, \mathbf{w}) = (1 - \epsilon) \sigma(\mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x})) + \epsilon [1 - \sigma(\mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}))]$$
$$= \epsilon + (1 - 2\epsilon) \sigma(\mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}))$$

• Classification into K > 2 classes: use 'softmax'

$$p(\mathcal{C}_k | \mathbf{x}, \mathbf{w}_1 \dots \mathbf{w}_K) = \frac{\exp(a_k)}{\sum_j \exp(a_j)}, \quad a_k = \mathbf{w}_k^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x})$$

• Likelihood for 1-of-K coding \mathbf{t}_n is then

$$p(\mathbf{t}_1 \dots \mathbf{t}_N | \mathbf{w}_1 \dots \mathbf{w}_K) = \prod_{n=1}^N \prod_{k=1}^K y_{nk}^{t_{nk}}$$

with $y_{nk} = \exp(a_{nk}) / \sum_j \exp(a_{nj})$ and $a_{nk} = \mathbf{w}_k^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}_n)$

6/18

Generative

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Prior and posterior

- Need to put a prior on w; could choose as for linear regression $p(w) = \mathcal{N}(w|0, \alpha^{-1}\mathbf{I})$
- Gives for posterior $p(\mathbf{w}|\mathbf{t}) \propto p(\mathbf{t}|\mathbf{w})p(\mathbf{w})$

$$\ln p(\mathbf{w}|\mathbf{t}) = -E(\mathbf{w}) + \text{const.}$$

$$E(\mathbf{w}) = \frac{\alpha}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w} - \sum_{n} [t_n \ln y_n + (1 - t_n) \ln(1 - y_n)]$$

• Need to normalize and then integrate to get predictions

$$p(\mathcal{C}_1|\mathbf{x}, \mathbf{t}) = \int p(\mathcal{C}_1|\mathbf{x}, \mathbf{w}) p(\mathbf{w}|\mathbf{t}) d\mathbf{w}$$

- Not a Gaussian integral but $p(\mathbf{w}|\mathbf{t})$ has a single maximum
- So approximate by a Gaussian around this maximum: Laplace approximation

Laplace approximation

In one dimension

- Consider a generic $p(w) = \exp[-E(w)]/Z$, Z = normalization constant ('partition function')
- If p(w) has a single maximum at w_0 , can expand around there:

$$E(w) \approx E(w_0) + \frac{1}{2}E''(w_0)(w - w_0)^2$$

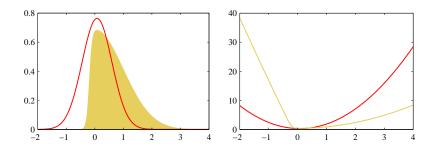
• Gives Gaussian approximation for p(w):

$$p(w) \approx q(w) = \frac{e^{-E(w_0)}}{Z} e^{-\frac{E''(w_0)}{2}(w-w_0)^2} = \mathcal{N}(w|w_0, 1/E''(w_0))$$

• Approximation for Z:

$$Z = e^{-E(w_0)} (2\pi)^{1/2} [E''(w_0)]^{-1/2}$$

Laplace approximation



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10 / 18

Laplace approximation

- Consider again $p(\mathbf{w}) = \exp[-E(\mathbf{w})]/Z$
- If $p(\mathbf{w})$ has a single maximum at \mathbf{w}_0 , can expand around there:

$$E(\mathbf{w}) \approx E(\mathbf{w}_0) + \frac{1}{2}(\mathbf{w} - \mathbf{w}_0)^{\mathrm{T}} \mathbf{A}(\mathbf{w} - \mathbf{w}_0)$$

where $\mathbf{A} = \nabla \nabla E(\mathbf{w})|_{\mathbf{w} = \mathbf{w}_0}$ = Hessian at minimum of E

• Gives Gaussian approximation for $p(\mathbf{w})$:

$$p(\mathbf{w}) \approx q(\mathbf{w}) = \frac{e^{-E(\mathbf{w}_0)}}{Z} e^{-\frac{1}{2}(\mathbf{w} - \mathbf{w}_0)^{\mathrm{T}} \mathbf{A}(\mathbf{w} - \mathbf{w}_0)} = \mathcal{N}(\mathbf{w} | \mathbf{w}_0, \mathbf{A}^{-1})$$

• Approximation for Z:

$$Z = e^{-E(\mathbf{w}_0)} (2\pi)^{M/2} |\mathbf{A}|^{-1/2}$$

11/18

Back to Bayesian logistic regression

• Posterior $p(\mathbf{w}|\mathbf{t}) = \exp[-E(\mathbf{w})]/Z$ with

$$E(\mathbf{w}) = \frac{\alpha}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w} - \sum_{n} [t_n \ln y_n + (1 - t_n) \ln(1 - y_n)]$$

- $E(\mathbf{w})$ convex, single minimum, Hessian $\alpha \mathbf{I} + \mathbf{\Phi}^{\mathrm{T}} \mathbf{R} \mathbf{\Phi}$
- ullet Find minimum $\mathbf{w}_{\mathrm{MAP}}$, call Hessian there \mathbf{S}_{N}^{-1}
- Then Laplace approximation for posterior is

$$p(\mathbf{w}|\mathbf{t}) \approx q(\mathbf{w}) = \mathcal{N}(\mathbf{w}|\mathbf{w}_{\text{MAP}}, \mathbf{S}_N)$$

Predictive distribution

• Use approximate posterior:

$$p(\mathcal{C}_1|\mathbf{x}, \mathbf{t}) \approx \int p(\mathcal{C}_1|\mathbf{x}, \mathbf{w}) q(\mathbf{w}) d\mathbf{w} = \int \sigma(\mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x})) q(\mathbf{w}) d\mathbf{w}$$

• Call $a = \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x})$, then a has Gaussian distribution, with

$$\mathbb{E}[a] = \int \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}) q(\mathbf{w}) d\mathbf{w} = \mathbf{w}_{\mathrm{MAP}}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x})$$
$$\mathbb{E}[a^{2}] = \int \boldsymbol{\phi}(\mathbf{x})^{\mathrm{T}} \mathbf{w} \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}) q(\mathbf{w}) d\mathbf{w}$$
$$= \boldsymbol{\phi}(\mathbf{x})^{\mathrm{T}} (\mathbf{w}_{\mathrm{MAP}} \mathbf{w}_{\mathrm{MAP}}^{\mathrm{T}} + \mathbf{S}_{N}) \boldsymbol{\phi}(\mathbf{x})$$

So

$$p(\mathcal{C}_1|\mathbf{x}, \mathbf{t}) \approx \int \sigma(a) \mathcal{N}(a|\mathbf{w}_{MAP}^{T} \boldsymbol{\phi}(\mathbf{x}), \boldsymbol{\phi}(\mathbf{x})^{T} \mathbf{S}_N \boldsymbol{\phi}(\mathbf{x})) da$$

• Can be done numerically, or analytically for inverse probit

13/18

3

Bayesian classification



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Generative classification

- We model joint distribution $p(\mathbf{x}, C_k)$, rather than conditional distribution $p(C_k | \mathbf{x})$ of class labels
- Normally separate $p(\mathbf{x}, C_k) = p(\mathbf{x}|C_k)p(C_k)$
- Class probabilities $p(\mathcal{C}_k|\boldsymbol{\pi}) = \pi_k$
- Class conditional densities e.g.

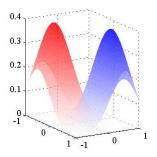
$$p(\mathbf{x}|\mathcal{C}_k, \{\boldsymbol{\mu}_j\}, \boldsymbol{\Sigma}) = \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_k, \boldsymbol{\Sigma})$$

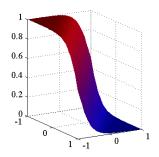
For two classes this gives

$$p(\mathcal{C}_1|\mathbf{x}) = \sigma(\mathbf{w}^{\mathrm{T}}\mathbf{x} + w_0)$$

- Linear discriminant as before, logistic sigmoid arises naturally
- If classes have different Σ , get quadratic discriminant

Illustration





Bayesian logistic regression

Maximum likelihood inference

- Consider two classes, so that $\pi_1\equiv\pi,\,\pi_2=1-\pi$
- Training data: N inputs \mathbf{x}_n , N outputs $t_n \in \{0, 1\}$
- Collect into $\mathbf{X}^{\mathrm{T}} = (\mathbf{x}_1, \dots, \mathbf{x}_N)$ and $\mathbf{t} = (t_1, \dots, t_N)$

•
$$t_n = 1$$
 for \mathcal{C}_1 , $t_n = 0$ for \mathcal{C}_2

- Likelihood: $p(\mathbf{x}, t = 1) = p(\mathbf{x}|\mathcal{C}_1)p(\mathcal{C}_1) = \pi \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_1, \boldsymbol{\Sigma})$
- Similarly, $p(\mathbf{x}, t = 0) = p(\mathbf{x}|\mathcal{C}_2)p(\mathcal{C}_2) = (1 \pi)\mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_2, \boldsymbol{\Sigma})$
- Overall data likelihood $p(\mathbf{t},\mathbf{X}|\pi, \boldsymbol{\mu}_1, \boldsymbol{\mu}_2, \boldsymbol{\Sigma}) =$

$$\prod_{n=1}^{N} \left[\pi \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_1, \boldsymbol{\Sigma}) \right]^{t_n} \left[(1 - \pi) \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_2, \boldsymbol{\Sigma}) \right]^{1 - t_n}$$

• Can be maximized in closed form

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Bayesian inference

- Allow $\mathbf{\Sigma}_1
 eq \mathbf{\Sigma}_2$ now so each $p(\mathbf{x}|\mathcal{C}_k)$ has its own parameters
- Likelihood factorizes: $p(\mathbf{t}, \mathbf{X} | \pi, \boldsymbol{\mu}_1, \boldsymbol{\mu}_2, \boldsymbol{\Sigma}) =$

$$\prod_{n=1}^{N} \pi^{t_n} (1-\pi)^{1-t_n} \prod_{n:t_n=1} \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_1, \boldsymbol{\Sigma}_1) \prod_{n:t_n=0} \mathcal{N}(\mathbf{x}_n | \boldsymbol{\mu}_2, \boldsymbol{\Sigma}_2)$$

- So if prior factorizes into $p(\pi)p(\mu_1, \Sigma_1)p(\mu_2, \Sigma_2)$, then posterior $p(\pi, \mu_1, \Sigma_1, \mu_2, \Sigma_2 | \mathbf{t}, \mathbf{X})$ factorizes in the same way
- Predictive distributions simplify accordingly, e.g. $\mathit{p}(\mathbf{x},\mathcal{C}_1) =$

$$\int d\pi \, \pi \, p(\pi | \mathbf{t}, \mathbf{X}) \times \int d\boldsymbol{\mu}_1 d\boldsymbol{\Sigma}_1 \mathcal{N}(\mathbf{x} | \boldsymbol{\mu}_1, \boldsymbol{\Sigma}_1) p(\boldsymbol{\mu}_1, \boldsymbol{\Sigma}_1 | \mathbf{t}, \mathbf{X})$$

- Effectively, each class density models $p(\mathbf{x}|\mathcal{C}_k)$ is learnt separately from training data with class label k
- Conjugate priors $p(\mu_k, \Sigma_k)$: Gamma-Wishart