

Problems for Lecture 10: Answers

- (a) $3\mathbf{A} = 3 \begin{pmatrix} 2 & 3 \\ 4 & 6 \end{pmatrix} = \begin{pmatrix} 6 & 9 \\ 12 & 18 \end{pmatrix},$
1. (b) $\mathbf{A} + \mathbf{B} = \begin{pmatrix} 2 & 3 \\ 4 & 6 \end{pmatrix} + \begin{pmatrix} 2 & -1 \\ 5 & 4 \end{pmatrix} = \begin{pmatrix} 4 & 2 \\ 9 & 10 \end{pmatrix},$
- (c) $3\mathbf{B} - 2\mathbf{C} = 3 \begin{pmatrix} 2 & -1 \\ 5 & 4 \end{pmatrix} - 2 \begin{pmatrix} -4 & 2 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 6 & -3 \\ 15 & 12 \end{pmatrix} + \begin{pmatrix} 8 & -4 \\ 0 & -2 \end{pmatrix} = \begin{pmatrix} 14 & -7 \\ 15 & 10 \end{pmatrix}.$
2. (a) $\mathbf{r}_1 = \begin{pmatrix} 2 & 3 \\ 4 & 6 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 2 \cdot 3 + 3 \cdot 4 \\ 4 \cdot 3 + 6 \cdot 4 \end{pmatrix} = \begin{pmatrix} 18 \\ 36 \end{pmatrix},$
- (b) $\mathbf{r}_2 = \begin{pmatrix} 2 & -1 \\ 5 & 4 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 2 \cdot 3 + (-1) \cdot 4 \\ 5 \cdot 3 + 4 \cdot 4 \end{pmatrix} = \begin{pmatrix} 2 \\ 31 \end{pmatrix},$
- (c) $\mathbf{r}_3 = \mathbf{r}_1 + \mathbf{r}_2 = \begin{pmatrix} 18 \\ 36 \end{pmatrix} + \begin{pmatrix} 2 \\ 31 \end{pmatrix} = \begin{pmatrix} 20 \\ 67 \end{pmatrix},$
- (d) $\mathbf{r}_4 = \begin{pmatrix} 4 & 2 \\ 9 & 10 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 4 \cdot 3 + 2 \cdot 4 \\ 9 \cdot 3 + 10 \cdot 4 \end{pmatrix} = \begin{pmatrix} 20 \\ 67 \end{pmatrix}.$

The transformation effected by the sum of the two matrices ($\mathbf{A} + \mathbf{B}$) is the same as the sum of the two transformations \mathbf{A} and \mathbf{B} .

Let $\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$, $\mathbf{B} = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}$. Then $\mathbf{A}\mathbf{r} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a_{11}x + a_{12}y \\ a_{21}x + a_{22}y \end{pmatrix}$ and

$\mathbf{B}\mathbf{r} = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} b_{11}x + b_{12}y \\ b_{21}x + b_{22}y \end{pmatrix}$ so that

$$\begin{aligned} \mathbf{A}\mathbf{r} + \mathbf{B}\mathbf{r} &= \begin{pmatrix} a_{11}x + a_{12}y + b_{11}x + b_{12}y \\ a_{21}x + a_{22}y + b_{21}x + b_{22}y \end{pmatrix}, \text{ using the property of matrix addition} \\ &= \begin{pmatrix} (a_{11} + b_{11})x + (a_{12} + b_{12})y \\ (a_{21} + b_{21})x + (a_{22} + b_{22})y \end{pmatrix}, \text{ using the property for real numbers} \\ &= \begin{pmatrix} a_{11} + b_{11} & a_{12} + b_{12} \\ a_{21} + b_{21} & a_{22} + b_{22} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}, \text{ using then definition of matrix multiplication} \\ &= \left(\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} + \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix} \right) \begin{pmatrix} x \\ y \end{pmatrix}, \text{ using the definition of matrix addition} \\ &= (\mathbf{A} + \mathbf{B})\mathbf{r}. \end{aligned}$$

3. (a) $\mathbf{AB} = \begin{pmatrix} 2 & 3 \\ 4 & 6 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 5 & 4 \end{pmatrix} = \begin{pmatrix} 2 \cdot 2 + 3 \cdot 5 & 2 \cdot (-1) + 3 \cdot 4 \\ 4 \cdot 2 + 6 \cdot 5 & 4 \cdot (-1) + 6 \cdot 4 \end{pmatrix} = \begin{pmatrix} 19 & 10 \\ 38 & 20 \end{pmatrix},$
- (b) $\mathbf{BC} = \begin{pmatrix} 2 & -1 \\ 5 & 4 \end{pmatrix} \begin{pmatrix} -4 & 2 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 \cdot (-4) + (-1) \cdot 0 & 2 \cdot 2 + (-1) \cdot 1 \\ 5 \cdot (-4) + 4 \cdot 0 & 5 \cdot 2 + 4 \cdot 1 \end{pmatrix} = \begin{pmatrix} -8 & 3 \\ -20 & 14 \end{pmatrix},$
- (c) $\mathbf{CB} = \begin{pmatrix} -4 & 2 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & -1 \\ 5 & 4 \end{pmatrix} = \begin{pmatrix} (-4) \cdot 2 + 2 \cdot 5 & (-4) \cdot (-1) + 2 \cdot 4 \\ 0 \cdot 2 + 1 \cdot 5 & 0 \cdot (-1) + 1 \cdot 4 \end{pmatrix} = \begin{pmatrix} 2 & 12 \\ 5 & 4 \end{pmatrix},$
- (d) $\mathbf{AC} = \begin{pmatrix} 2 & 3 \\ 4 & 6 \end{pmatrix} \begin{pmatrix} -4 & 2 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 \cdot (-4) + 3 \cdot 0 & 2 \cdot 2 + 3 \cdot 1 \\ 4 \cdot (-4) + 6 \cdot 0 & 4 \cdot 2 + 6 \cdot 1 \end{pmatrix} = \begin{pmatrix} -8 & 7 \\ -16 & 14 \end{pmatrix},$
- (e) $(\mathbf{AB})\mathbf{C} = \begin{pmatrix} 19 & 10 \\ 38 & 20 \end{pmatrix} \begin{pmatrix} -4 & 2 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 19 \cdot (-4) + 10 \cdot 0 & 19 \cdot 2 + 10 \cdot 1 \\ 38 \cdot (-4) + 20 \cdot 0 & 38 \cdot 2 + 20 \cdot 1 \end{pmatrix} = \begin{pmatrix} -76 & 48 \\ -152 & 96 \end{pmatrix},$
- (f) $\mathbf{A}(\mathbf{BC}) = \begin{pmatrix} 2 & 3 \\ 4 & 6 \end{pmatrix} \begin{pmatrix} -8 & 3 \\ -20 & 14 \end{pmatrix} = \begin{pmatrix} 2 \cdot (-8) + 3 \cdot (-20) & 2 \cdot 3 + 3 \cdot 14 \\ 4 \cdot (-8) + 6 \cdot (-20) & 4 \cdot 3 + 6 \cdot 14 \end{pmatrix} = \begin{pmatrix} -76 & 48 \\ -152 & 96 \end{pmatrix},$
- (g) $(\mathbf{A} + \mathbf{B})\mathbf{C} = \begin{pmatrix} 4 & 2 \\ 9 & 10 \end{pmatrix} \begin{pmatrix} -4 & 2 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 4 \cdot (-4) + 2 \cdot 0 & 4 \cdot 2 + 2 \cdot 1 \\ 9 \cdot (-4) + 10 \cdot 0 & 9 \cdot 2 + 10 \cdot 1 \end{pmatrix} = \begin{pmatrix} -16 & 10 \\ -36 & 28 \end{pmatrix},$
- (h) $\mathbf{AC} + \mathbf{BC} = \begin{pmatrix} -8 & 7 \\ -16 & 14 \end{pmatrix} + \begin{pmatrix} -8 & 3 \\ -20 & 14 \end{pmatrix} = \begin{pmatrix} -16 & 10 \\ -36 & 28 \end{pmatrix}.$

These special cases illustrate general properties of matrix manipulation,

Matrix multiplication is associative $(\mathbf{AB})\mathbf{C} = \mathbf{A}(\mathbf{BC})$ ((e) and (f)).

Matrix multiplication is distributive $(\mathbf{A} + \mathbf{B})\mathbf{C} = \mathbf{AC} + \mathbf{BC}$ ((g) and (h))

Matrix multiplication is **not**, in general, commutative $\mathbf{BC} \neq \mathbf{CB}$ ((b) and (c)).

4. Matrix multiplication is only defined between matrices \mathbf{A} and \mathbf{B} if the number of columns in the matrix \mathbf{A} equals the number of rows in the matrix \mathbf{B} . For example, if \mathbf{A} is an $m \times p$ matrix and \mathbf{B} is a $p \times n$ matrix, the matrix product is well-defined and \mathbf{AB} is an $m \times n$ matrix. Note that \mathbf{BA} is **not** well-defined unless $n = m$ in which case \mathbf{BA} is a $p \times p$ matrix. \mathbf{P} is a 2×4 matrix, \mathbf{Q} is a 3×2 matrix, and \mathbf{R} is a 3×3 matrix. Hence only \mathbf{QP} (a 3×4 matrix), \mathbf{RQ} (a 3×3 matrix), and $\mathbf{RR} = \mathbf{R}^2$ (a 3×3 matrix) are well-defined. All other combinations are meaningless. We find:

$$\begin{aligned} \mathbf{QP} &= \begin{pmatrix} 2 & 4 \\ 1 & -1 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} 2 & 3 & 1 & -4 \\ 2 & 1 & 0 & 5 \end{pmatrix} = \begin{pmatrix} 2 \cdot 2 + 4 \cdot 2 & 2 \cdot 3 + 4 \cdot 1 & 2 \cdot 1 + 4 \cdot 0 & 2 \cdot (-4) + 4 \cdot 5 \\ 1 \cdot 2 + (-1) \cdot 2 & 1 \cdot 3 + (-1) \cdot 1 & 1 \cdot 1 + (-1) \cdot 0 & 1 \cdot (-4) + (-1) \cdot 5 \\ 3 \cdot 2 + (-1) \cdot 2 & 3 \cdot 3 + (-1) \cdot 1 & 3 \cdot 1 + (-1) \cdot 0 & 3 \cdot (-4) + (-1) \cdot 5 \end{pmatrix} \\ &= \begin{pmatrix} 12 & 10 & 2 & 12 \\ 0 & 2 & 1 & -9 \\ 4 & 8 & 3 & -17 \end{pmatrix} \end{aligned}$$

$$\mathbf{RQ} = \begin{pmatrix} 2 & 1 & 3 \\ 4 & -1 & -2 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 4 \\ 1 & -1 \\ 3 & -1 \end{pmatrix} = \begin{pmatrix} 2 \cdot 2 + 1 \cdot 1 + 3 \cdot 3 & 2 \cdot 4 + 1 \cdot (-1) + 3 \cdot (-1) \\ 4 \cdot 2 + (-1) \cdot 1 + (-2) \cdot 3 & 4 \cdot 4 + (-1) \cdot (-1) + (-2) \cdot (-1) \\ (-1) \cdot 2 + 0 \cdot 1 + 1 \cdot 3 & (-1) \cdot 4 + 0 \cdot (-1) + 1 \cdot (-1) \end{pmatrix} = \begin{pmatrix} 14 & 4 \\ 1 & 19 \\ 1 & -5 \end{pmatrix}$$

$$\begin{aligned} \mathbf{R}^2 &= \begin{pmatrix} 2 & 1 & 3 \\ 4 & -1 & -2 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 1 & 3 \\ 4 & -1 & -2 \\ -1 & 0 & 1 \end{pmatrix} \\ &= \begin{pmatrix} 2 \cdot 2 + 1 \cdot 4 + 3 \cdot (-1) & 2 \cdot 1 + 1 \cdot (-1) + 3 \cdot 0 & 2 \cdot 3 + 1 \cdot (-2) + 3 \cdot 1 \\ 4 \cdot 2 + (-1) \cdot 4 + (-2) \cdot (-1) & 4 \cdot 1 + (-1) \cdot (-1) + (-2) \cdot 0 & 4 \cdot 3 + (-1) \cdot (-2) + (-2) \cdot 1 \\ (-1) \cdot 2 + 0 \cdot 4 + 1 \cdot (-1) & (-1) \cdot 1 + 0 \cdot (-1) + 1 \cdot 0 & (-1) \cdot 3 + 0 \cdot (-2) + 1 \cdot 1 \end{pmatrix} \\ &= \begin{pmatrix} 5 & 1 & 7 \\ 6 & 5 & 12 \\ -3 & -1 & -2 \end{pmatrix}. \end{aligned}$$

5. Define the inverse matrix $\mathbf{A}^{-1} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$. This matrix must satisfy $\mathbf{A}^{-1}\mathbf{A} = \mathbf{I}$ and

$$\mathbf{AA}^{-1} = \mathbf{I}. \text{ The first equation implies } \mathbf{AA}^{-1} = \mathbf{I} \Leftrightarrow \begin{pmatrix} 9 & 6 \\ 5 & 3 \end{pmatrix} \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \text{ which is}$$

equivalent of a system of 4 equations with 4 unknowns (actually 2×2 Eqs. With 2 unknowns):

$$9a_{11} + 6a_{21} = 1$$

$$5a_{11} + 3a_{21} = 0$$

$$9a_{12} + 6a_{22} = 0 \text{ These are solve, for example by using Cramer's rule:}$$

$$5a_{12} + 3a_{22} = 1$$

$$a_{11} = \frac{\begin{vmatrix} 1 & 6 \\ 0 & 3 \end{vmatrix}}{\begin{vmatrix} 9 & 6 \\ 5 & 3 \end{vmatrix}} = \frac{3}{-3} = -1; \quad a_{21} = \frac{\begin{vmatrix} 9 & 1 \\ 5 & 0 \end{vmatrix}}{\begin{vmatrix} 9 & 6 \\ 5 & 3 \end{vmatrix}} = \frac{-5}{-3} = \frac{5}{3}; \quad a_{12} = \frac{\begin{vmatrix} 0 & 6 \\ 1 & 3 \end{vmatrix}}{\begin{vmatrix} 9 & 6 \\ 5 & 3 \end{vmatrix}} = \frac{-6}{-3} = 2; \quad a_{22} = \frac{\begin{vmatrix} 9 & 0 \\ 5 & 1 \end{vmatrix}}{\begin{vmatrix} 9 & 6 \\ 5 & 3 \end{vmatrix}} = \frac{9}{-3} = -3.$$

We check that $\begin{pmatrix} -1 & 2 \\ \frac{5}{3} & -3 \end{pmatrix} \begin{pmatrix} 9 & 6 \\ 5 & 3 \end{pmatrix} = \begin{pmatrix} 9 & 6 \\ 5 & 3 \end{pmatrix} \begin{pmatrix} -1 & 2 \\ \frac{5}{3} & -3 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$, confirming that indeed

the inverse matrix is $\mathbf{A}^{-1} = \begin{pmatrix} -1 & 2 \\ \frac{5}{3} & -3 \end{pmatrix}$.

6. Applying the matrix $\mathbf{R} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ to a vector \mathbf{r} rotates it through an angle of θ counter-clock wise. Hence

$$\mathbf{R}\mathbf{r} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} 3 \cos \theta - 4 \sin \theta \\ 3 \sin \theta + 4 \cos \theta \end{pmatrix} = \begin{pmatrix} \frac{3}{2} - 2\sqrt{3} \\ 3\frac{\sqrt{3}}{2} + 2 \end{pmatrix} \approx \begin{pmatrix} -1.964 \\ 4.598 \end{pmatrix} \text{ for } \theta = 60^\circ.$$

7. (a) $3\mathbf{M} = 3 \begin{pmatrix} 4 & 1 \\ 3 & 2 \end{pmatrix} = \begin{pmatrix} 12 & 3 \\ 9 & 6 \end{pmatrix}$, (b) $\det \mathbf{M} = \begin{vmatrix} 4 & 1 \\ 3 & 2 \end{vmatrix} = 4 \cdot 2 - 3 \cdot 1 = 5$,

(c) $\det(3\mathbf{M}) = \begin{vmatrix} 12 & 3 \\ 9 & 6 \end{vmatrix} = 12 \cdot 6 - 9 \cdot 3 = 45 = 3^2 \cdot 5$.

A determinant is multiplied by a factor r if all elements of one row (or column) are multiplied by r (see property 2, Fact Sheet 6). Therefore, if all elements of all n rows are multiplied by r , which is what happens if the parent matrix is multiplied by a factor r , the determinant will be multiplied by r^n , that is, if \mathbf{A} is an $n \times n$ matrix, then $\det r\mathbf{A} = r^n \det \mathbf{A}$.