

Classwork 5 – ANSWERS (corrected)

- (a) The magnitude of \mathbf{u} ($|\mathbf{u}| = \sqrt{\mathbf{u} \cdot \mathbf{u}}$) is the root of the sum of the squares of the components, so $u_x^2 + u_y^2 = v_x^2 + v_y^2 = 1$ in this case. The two vectors are orthogonal if $\mathbf{u} \cdot \mathbf{v} = 0$, so $u_x v_x + u_y v_y = 0$. In matrix form, the conditions are $\mathbf{v}^T \mathbf{v} = \mathbf{u}^T \mathbf{u} = 1$ and $\mathbf{v}^T \mathbf{u} = \mathbf{u}^T \mathbf{v} = 0$.

(b) $\hat{\mathbf{a}} = \begin{pmatrix} 3/5 \\ -4/5 \end{pmatrix}$ and $\hat{\mathbf{b}} = \begin{pmatrix} \pm 4/5 \\ \pm 3/5 \end{pmatrix}$.

(c) $\begin{pmatrix} u_x & u_y \\ v_x & v_y \end{pmatrix} \begin{pmatrix} u_x & v_x \\ u_y & v_y \end{pmatrix} = \begin{pmatrix} u_x^2 + u_y^2 & u_x v_x + u_y v_y \\ u_x v_x + u_y v_y & v_x^2 + v_y^2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ using the conditions in (a).

(d) $\begin{pmatrix} q_x \\ q_y \end{pmatrix} = \begin{pmatrix} cp_x + dp_y \\ ep_x + fp_y \end{pmatrix}$ so $q_x^2 + q_y^2 = (c^2 + e^2)p_x^2 + (d^2 + f^2)p_y^2 + 2p_x p_y (cd + ef) = p_x^2 + p_y^2$.

The conditions for this to be true are $c^2 + e^2 = d^2 + f^2 = 1$ and $cd + ef = 0$, which are exactly the same as the conditions on the elements of \mathbf{M} in part (c).

(e) $\mathbf{q}^T = \mathbf{p}^T \mathbf{N}^T$.

(f) $\mathbf{q}^T \mathbf{h} = \mathbf{p}^T \mathbf{N}^T \mathbf{N} \mathbf{g}$ using the result of part (e), so $\mathbf{q}^T \mathbf{h} = \mathbf{p}^T \mathbf{g}$ if $\mathbf{N}^T \mathbf{N} = \mathbf{U}$.

(g) Yes.

(h) $\mathbf{L}_1 = \begin{pmatrix} 3/5 & 4/5 \\ -4/5 & 3/5 \end{pmatrix}$ and $\mathbf{L}_2 = \begin{pmatrix} 3/5 & -4/5 \\ -4/5 & -3/5 \end{pmatrix}$. The first represents a clockwise rotation of 53.13° , whereas $\mathbf{L}_2 = \mathbf{L}_1 \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$, which represents a reflection in the x -axis ($y \rightarrow -y$)

followed by a 53.13° clockwise rotation.

(i) $\mathbf{t}_1 = \begin{pmatrix} 3/5 & 4/5 \\ -4/5 & 3/5 \end{pmatrix} \begin{pmatrix} -5 \\ 7 \end{pmatrix} = \begin{pmatrix} 13/5 \\ 41/5 \end{pmatrix}$; $\mathbf{t}_2 = \begin{pmatrix} 3/5 & -4/5 \\ -4/5 & -3/5 \end{pmatrix} \begin{pmatrix} -5 \\ 7 \end{pmatrix} = \begin{pmatrix} -43/5 \\ -1/5 \end{pmatrix}$.

The magnitude of all three vectors is $\sqrt{74}$.

It follows that $\mathbf{s} \cdot \mathbf{t}_1 = \frac{-65 + 287}{5 \times 74} = 0.6$ which corresponds to an angle of 53.13° , and

$$\mathbf{s} \cdot \mathbf{t}_2 = \frac{215 - 7}{5 \times 74} = 0.5622 \text{ which corresponds to an angle of } 55.79^\circ.$$

Relative to the negative x -axis, the vector \mathbf{s} lies at 54.46° clockwise, the vector \mathbf{t}_1 lies at 107.59° clockwise, and the vector \mathbf{t}_2 lies at 1.33° anti-clockwise. The latter can be

obtained by reflection of \mathbf{s} in the x -axis to produce $\begin{pmatrix} -5 \\ -7 \end{pmatrix}$ (54.46° anti-clockwise),

followed by a 53.13° clockwise rotation.