- 1. (i) Define a projective curve in \mathbb{CP}^2 and explain why the definition gives a well-defined subset of \mathbb{CP}^2 . What condition should the defining polynomial of a projective curve satisfy so that the polynomial is uniquely determined by the subset of \mathbb{CP}^2 (up to scalar multiplication)?
 - (ii) Define irreducible and reducible projective curves.
 - (iii) Define a singular point of a projective curve C. Prove that any reducible projective curve C in \mathbb{CP}^2 has at least one singular point.
 - (iv) Prove that any irreducible cubic projective curve C in \mathbb{CP}^2 has at most 1 singular point. (You may use any standard facts about the relation between intersection multiplicities and the multiplicities of singular points provided you state them clearly).
- 2. Consider the following family of complex cubics defined on \mathbb{C}^3

$$P_{\mu,\lambda} = \mu(x^3 + y^3 + z^3) + 3\lambda xyz,$$

where μ and λ are complex numbers, not both zero.

- (i) Prove that if the projective curve $C_{\mu,\lambda}$ defined by $P_{\mu,\lambda}$ is singular then $\mu = 0$ or $\left(\frac{\lambda}{\mu}\right)^3 = -1.$
- (ii) If $\mu = 0$ find the singular points of $C_{0,\lambda}$ and show that $C_{0,\lambda}$ is a union of three distinct lines (which you should explicitly identify). What is the relationship between the geometry of these 3 lines and the singular points of $C_{0,\lambda}$?
- (iii) If $C_{\mu,\lambda}$ is singular and $\mu \neq 0$, prove that at any singular point p = [x, y, z], the three ratios $\frac{x}{y}, \frac{x}{z}, \frac{y}{z}$ are all cube roots of 1. Hence or otherwise, find the three singular points of $C_{\mu,\lambda}$ in the case where $\left(\frac{\lambda}{\mu}\right) = -\exp(\frac{2\pi i}{3})$.
- (iv) By considering lines passing through these singular points show that when $\left(\frac{\lambda}{\mu}\right) = -\exp(\frac{2\pi i}{3})$, $C_{\mu,\lambda}$ is a union of three distinct lines, which you should find.

- 3. Let C be a projective curve in \mathbb{CP}^2 defined by the homogeneous polynomial P of degree d.
 - (i) Define an inflection point of C.
 - (ii) Prove that if $d \ge 3$, and C is nonsingular then it has at least one and at most 3d(d-2) points of inflection. (You may assume that every point of an irreducible projective curve of degree d is an inflection point if and only if d = 1.)
 - (iii) Suppose that C is nonsingular and does not contain the point [0, 1, 0]. Define the map $\phi: C \to \mathbb{CP}^1$ by

$$\phi([x, y, z]) = [x, z].$$

Define the ramification index $\nu_{\phi}[a, b, c]$ of ϕ at $[a, b, c] \in C$.

(iv) Prove that $\nu_{\phi}[a, b, c] > 1$ if and only if $[a, b, c] \in C$ and the tangent line to C at [a, b, c] contains the point [0, 1, 0], and that $\nu_{\phi}[a, b, c] > 2$ if and only if [a, b, c] is a point of inflection of C and the tangent line to C at [a, b, c] contains the point [0, 1, 0]. (You may use that fact that the Hessian \mathcal{H}_P satisfies

$$z^{2}\mathcal{H}_{P}(a,b,c) = (d-1)^{2} \det \begin{pmatrix} P_{xx} & P_{xy} & P_{x} \\ P_{xy} & P_{yy} & P_{y} \\ P_{x} & P_{y} & dP/(d-1) \end{pmatrix}.)$$

4. (i) The Open Mapping Theorem for Riemann surfaces says that if f : R → S is a non-constant holomorphic map between Riemann surfaces R and S and R is connected, then f(R) is an open subset of S.
Use this result to prove that a nonconstant holomorphic map f : R → S between

connected Riemann surfaces R and S is surjective when R is compact. Deduce that S is also compact in this case.

- (ii) Using part (i) or otherwise, prove that if R is a compact connected Riemann surface then there are no nonconstant holomorphic functions $f : R \to \mathbb{C}$.
- (iii) Let S be a compact connected Riemann surface of genus zero. Assuming that the Riemann-Roch theorem applies to S, show that if p is any point on S and D is the divisor D = p, then l(D) = 2. State clearly any result you use.
- (iv) Deduce that there exists a meromorphic function f on S with a simple pole at p and no other poles.
- (v) Let f be a meromorphic function on S with the properties given in part (iv). Show that $f: S \to \mathbb{CP}^1$ is a holomorphic bijection. (You may use the fact that a nonconstant holomorphic map $f: R \to S$ between connected compact Riemann surfaces takes each value in S the same number of times counting multiplicity.)
- 5. (i) Define a *holomorphic atlas* on a surface.
 - (ii) Write down a holomorphic atlas on $\mathbb{CP}^1 = \mathbb{C} \cup \{\infty\}$, verifying that the atlas is holomorphic.
 - (iii) Give two definitions of a meromorphic differential on a Riemann surface. (One definition should be in terms of pairs of meromorphic functions. The other should be in terms of a collection of local meromorphic functions associated to a holomorphic atlas). Prove that these two definitions are equivalent. (You may assume that every Riemann surface admits at least one nonconstant meromorphic function.)
 - (iv) The holomorphic differential dz on \mathbb{C} extends to a meromorphic differential on $\mathbb{CP}^1 = \mathbb{C} \cup \{\infty\}$. Find the poles of dz viewed as a meromorphic differential on \mathbb{CP}^1 and at each pole find its order.