IMPERIAL COLLEGE LONDON

DEPARTMENT OF ELECTRICAL AND ELECTRONIC ENGINEERING **EXAMINATIONS 2006**

EEE/ISE PART II: MEng, BEng and ACGI

SIGNALS AND LINEAR SYSTEMS

Corrected Copy

None

Wednesday, 7 June 2:00 pm

Time allowed: 2:00 hours

There are FOUR questions on this paper.

Q1 is compulsory. Answer Q1 and any two of questions 2-4. Q1 carries 40% of the marks. Questions 2 to 4 carry equal marks (30% each).

Any special instructions for invigilators and information for candidates are on page 1.

Examiners responsible

First Marker(s): P.T. Stathaki,

Second Marker(s): A.G. Constantinides,

1.

Consider the discrete-time system with the following input-output relationship

$$y[n] = \frac{x[n] - x[n-1]}{2} \tag{1}$$

with x[n] the input of the system and y[n] the output of the system.

(i) Is this system linear and time-invariant? Justify your answer.

[5]

(ii) Find the impulse response h[n] of the system and express it compactly in a mathematical form. Sketch the impulse response.

[5]

(iii) Find the step response s[n] of the system and express it compactly in a mathematical form. Sketch the step response.

[5]

(iv) By performing the discrete time convolution y[n] = x[n] * h[n] find the output y[n] of the system when the input is given by

 $x[n] = \begin{cases} n, & n = 0,1,2,3,4\\ 0, & \text{otherwise.} \end{cases}$ (2)

Verify that the output is indeed the output expected from the filter defined in Equation (1) above, when the input is the signal x[n] defined in Equation (2) above.

[5]

(v) Consider a discrete signal x[n] with Discrete Time Fourier Transform $X(e^{j\omega})$. Find the Discrete Time Fourier Transform of the signal $x[n-n_0]$ with n_0 any integer.

[5]

(vi) Find the Discrete Time Fourier Transform of the signal x[n] defined in (iv).

[5]

(vii) Consider a discrete signal x[n] with z-transform X(z). Find the z-transform of the signal $x[n-n_0]$ with n_0 any integer.

[5]

(viii) Find the z-transform of the output y[n] of the system defined in Equation (1) above, when the input is the function x[n] defined in (iv).

[5]

- 2.
- (a) Consider a discrete, real and even signal $x_1[n]$ that is periodic with period N=7 and fundamental frequency $\omega_0 = \frac{2\pi}{N}$.
 - (i) Prove that the Fourier series coefficients c_k of $x_1[n]$ given by

$$c_k = \frac{1}{N} \sum_{n=0}^{N-1} x_1[n] e^{-jk(2\pi/N)n}$$

are real and even.

[6]

(ii) Show that the coefficients c_k are periodic with respect to k with period N=7.

[6]

(iii) Given that

$$c_{15} = 1$$
, $c_{16} = 2$, $c_{17} = 3$,

determine the values of c_{-1} , c_{-2} , c_{-3} .

[6]

(**Definition:** A discrete signal x[n] is even if x[-n] = x[n]).

(b) Find the Discrete Time Fourier Transform of the discrete signal $x_2[n] = a^n u[n], |a| < 1$, where u[n] is the discrete unit step function defined as

$$u[n] = \begin{cases} 1, & n \ge 0 \\ 0, & \text{otherwise.} \end{cases}$$

You may wish to use the relationship $\sum_{n=0}^{+\infty} x^n = \frac{1}{1-x}$, if |x| < 1.

[6]

(c) The input x[n] and output y[n] of a stable and causal linear, time-invariant system are related by the difference equation

$$y[n] - \frac{5}{6}y[n-1] + \frac{1}{6}y[n-2] = -x[n]$$
.

Find the impulse response of this system.

[6]

- 3.
- (a) Consider a continuous-time signal x(t) which is sampled uniformly with sampling period T_s to obtain the signal $x_s(t) = x(t) \sum_{k=-\infty}^{+\infty} \delta(t kT_s)$, where $\delta(t)$ is the continuous-time impulse function.
 - (i) Prove that $x_s(t) = \frac{1}{T_s} x(t) \sum_{k=-\infty}^{+\infty} e^{jk\frac{2\pi}{T_s}t}$. [7]
 - (ii) Prove that the Fourier transform of the sampled signal $x_s(t)$ is $X_s(\omega) = \frac{1}{T_s} \sum_{k=-\infty}^{k=+\infty} X(\omega + k\omega_s), \omega_s = \frac{2\pi}{T_s}$ where $X(\omega)$ is the Fourier transform of the original signal x(t).
- (b) Consider a continuous-time signal x(t) with Fourier transform $X(\omega) = (1 \frac{|\omega|}{2\pi \times 10^3})\Pi(\frac{\omega}{4\pi \times 10^3})$ where ω is the angular frequency and $\Pi(\omega)$ is defined as:

$$\Pi(\omega) = \begin{cases} 1 & |\omega| < 0.5 \\ 0.5 & |\omega| = 0.5 \\ 0 & \text{otherwise.} \end{cases}$$

We sample x(t) uniformly with sampling period T_s to obtain the signal $x_s(t) = x(t) \sum_{k=-\infty}^{+\infty} \delta(t - kT_s)$.

- (i) How large can T_s be and yet allow perfect reconstruction of the continuous-time signal from its samples? [7]
- (ii) Sketch the Fourier transform of $x_s(t)$, $X_s(\omega)$, assuming $T_s = 0.1 \text{ms}$.

[8]

- 4.
- (a) (i) Find the analytical expression and the region of convergence (ROC) of the z-transform of the discrete causal signal $x[n] = a^n u[n-1]$, with a real and u[n] the discrete unit step function defined as

$$u[n] = \begin{cases} 1, & n \ge 0 \\ 0, & \text{otherwise.} \end{cases}$$

- [6]
- (ii) Find the analytical expression and the region of convergence (ROC) of the z-transform of the discrete anti-causal signal $x[n] = -a^n u[-n]$, with a real and u[n] the discrete unit step function.
 - [6]

For parts (a) (i), (a) (ii) you may wish to use the relationship
$$\sum_{n=0}^{+\infty} x^n = \frac{1}{1-x}$$
, if $|x| < 1$.

(b) Consider a linear, time-invariant system with input x[n] and output y[n] related by the difference equation

$$y[n] - \frac{9}{2}y[n-1] + 2y[n-2] = -7x[n].$$

Determine the impulse response and its z-transform in the following three cases:

- (i) The system is causal.
- (ii) The system is stable.
- (iii) The system is neither causal nor stable.

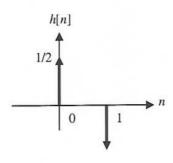
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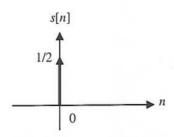
Answer

Yes, since if the inputs $x_1[n]$ and $x_2[n]$ produce the outputs $y_1[n]$ and $y_2[n]$ respectively, the input $a_1x_1[n] + a_2x_2[n]$ will produce the output $a_1y_1[n] + a_2y_2[n]$.

The impulse response of the system h[n] is defined as the output of the system when the input is the impulse function $\delta[n]$. Therefore, $h[n] = \frac{\delta[n] - \delta[n-1]}{2}$. This function is shown below:



The step response of the system s[n] is defined as the output of the system when the input is the unit step function u[n]. Therefore, $s[n] = \frac{u[n] - u[n-1]}{2} = \frac{\delta[n]}{2}$. This function is shown below:



(iv) This is defined as $y[n] = \sum_{k=-\infty}^{+\infty} x[k]h[n-k]$. In that case x[k] is non-zero if $0 \le k \le 4$ and h[n-k] is non-zero if $0 \le n-k \le 1 \Rightarrow -1 \le -n+k \le 0 \Rightarrow n-1 \le k \le n$. We may find three separate cases for which the two intervals overlap, and therefore the convolution is non-zero.

1. The lower bound of the function x[k] lies within the bounds of the function h[n-k], i.e., $n-1 \le 0 \le n \Rightarrow 0 \le n \le 1$.

In that case $y[n] = \sum_{k=-\infty}^{+\infty} x[k]h[n-k] = \sum_{k=0}^{n} \frac{1}{2}(\delta[n-k] - \delta[n-k-1])k = \frac{1}{2}n$. Therefore, y[0] = 0 and $y[1] = \frac{1}{2}$.

2. The bounds of the function h[n-k] are included within the bounds of the function x[k], $n-1>0 \Rightarrow n>1$ and $n \le 4$, i.e., $1 < n \le 4$

In that case $y[n] = \sum_{k=n-1}^{n} \frac{1}{2} (\delta[n-k] - \delta[n-k-1])k = -\frac{(n-1)}{2} + \frac{n}{2} = \frac{1}{2}$.

3. The upper bound of the function x[k] lies within the bounds of the function h[n-k], i.e., $n-1 \le 4 < n \Rightarrow 4 < n \le 5 \Rightarrow n=5$.

In that case $y[5] = \sum_{k=-\infty}^{+\infty} x[k]h[5-k] = x[5]h[0] + x[4]h[1] = 5\frac{1}{2} - 4\frac{1}{2} = \frac{1}{2}$. Thus,



$$y[n] = \begin{cases} 0 & n = 0\\ \frac{1}{2} & n = 1, 2, 3, 4, 5.\\ 0 & \text{otherwise} \end{cases}$$

From the relationship $y[n] = \frac{x[n] + x[n-1]}{2}$ we see that for the given function x[n] we can get y[n] as above, since:

$$y[0] = \frac{x[0] - x[-1]}{2} = 0$$
, $y[1] = \frac{x[1] - x[0]}{2} = \frac{1}{2}$, etc.

(v)
$$\sum_{n=-\infty}^{\infty} x[n-n_0]e^{-j\omega n} = \sum_{n=-\infty}^{\infty} x[n-n_0]e^{-j\omega(n-n_0)}e^{-j\omega n_0} = e^{-j\omega n_0}X(e^{j\omega})$$

(vi)
$$\sum_{n=1}^{4} ne^{-j\omega n} = e^{-j\omega} + 2e^{-2j\omega} + 3e^{-3j\omega} + 4e^{-4j\omega}$$

(vii)
$$\sum_{n=-\infty}^{\infty} x[n-n_0]z^{-n} = \sum_{n=-\infty}^{\infty} x[n-n_0]z^{-(n-n_0)}z^{-n_0} = z^{-n_0}X(z)$$

(viii)
$$Y(z) = X(z)\frac{1-z^{-1}}{2} = (z^{-1} + 2z^{-2} + 3z^{-3} + 4z^{-4})\frac{1-z^{-1}}{2}$$

(a) Consider the discrete, real and even signal x[n] that is periodic with period N=7 and fundamental frequency $\omega_0 = \frac{2\pi}{N}$. Suppose that the Fourier series coefficients of x(t) are c_k .

(i)
$$c_k = \frac{1}{N} \sum_{n=0}^{N-1} x_1 [n] e^{-jk(2\pi/N)n} \text{ and also}$$

$$c_k = \frac{1}{N} \sum_{n=-(N-1)}^{0} x_1 [n] e^{-jk(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{N-1} x_1 [-n] e^{jk(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{N-1} x_1 [n] e^{jk(2\pi/N)n} = c_k^*$$

$$c_{-k} = \frac{1}{N} \sum_{n=0}^{N-1} x_1 [n] e^{-jk(2\pi/N)(-n)} = \frac{1}{N} \sum_{n=0}^{-(N-1)} x_1 [-n] e^{-jk(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{-(N-1)} x_1 [n] e^{-jk(2\pi/N)n} = c_k$$

(ii)
$$c_{k+N} = \frac{1}{N} \sum_{n=0}^{N-1} x_1[n] e^{-j(k+N)(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{N-1} x_1[n] e^{-jk(2\pi/N)n} e^{-j2\pi n} = c_k$$

(iii) Since the Fourier series coefficients c_k will be real and even. Given that

$$c_{15} = 1$$
, $c_{16} = 2$, $c_{17} = 3$

determine the values of c_{-1} , c_{-2} , c_{-3}

$$c_{-1} = c_1 = c_{15} = 1$$

 $c_{-2} = c_2 = c_{16} = 2$
 $c_{-3} = c_3 = c_{17} = 3$

(b) Find the Fourier transform of the discrete signal $x[n] = a^n u[n], |a| < 1$.

In this case
$$X(e^{j\omega}) = \sum_{n=-\infty}^{+\infty} a^n u[n] e^{-j\omega n} = \sum_{n=0}^{+\infty} (ae^{-j\omega})^n = \frac{1}{1 - ae^{-j\omega}}, \ |a| < 1$$

(c) The input and output of a stable and causal LTI system are related by the differential equation

$$y[n] - \frac{5}{6}y[n-1] + \frac{1}{6}y[n-2] = -x[n]$$

Find the impulse response of this system.

We take the Fourier transform in both sides:

$$Y(e^{j\omega}) - \frac{5}{6}e^{-j\omega}Y(e^{j\omega}) + \frac{1}{6}e^{-2j\omega}Y(e^{j\omega}) = -X(e^{j\omega}) \Rightarrow$$

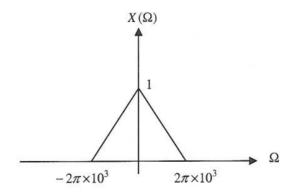
$$\frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{-1}{1 - \frac{5}{6}e^{-j\omega} + \frac{1}{6}e^{-2j\omega}} = \frac{-1}{(1 - \frac{1}{2}e^{-j\omega})(1 - \frac{1}{3}e^{-j\omega})} =$$

$$\frac{2}{(1 - \frac{1}{3}e^{-j\omega})} - \frac{3}{(1 - \frac{1}{2}e^{-j\omega})} \Rightarrow$$

$$h[n] = [2(\frac{1}{3})^n - 3(\frac{1}{2})^n]u[n]$$

3.

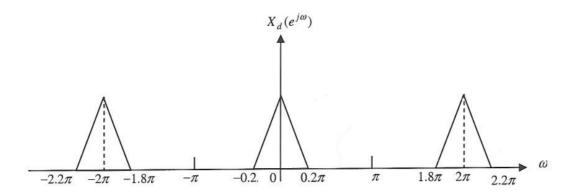
- (a) (i) The continuous-time impulse train $\sum\limits_{k=-\infty}^{\infty}\delta(t-kT)$ is a periodic function and therefore it can be written using Fourier series. The Fourier series coefficients are $c_k=\frac{1}{T_s}\int\limits_{-\frac{T_s}{2}}^{\frac{T_s}{2}}\delta(t)e^{-jk\omega_s t}dt=\frac{1}{T_s}$. Therefore, $x_s(t)=x(t)\sum\limits_{k=-\infty}^{+\infty}\delta(t-kT_s)=\frac{1}{T_s}x(t)\sum\limits_{k=-\infty}^{+\infty}e^{jk\frac{2\pi}{T_s}t}$
 - (ii) The Fourier transform of the signal $e^{j\omega_s t}x(t)$ is $X(j(\omega-\omega_s))$ and therefore the Fourier transform of the sampled signal $x_s(t)$ is $X_s(e^{j\omega}) = \frac{1}{T_s} \sum_{k=-\infty}^{k=+\infty} X(\omega+k\omega_s), \omega_s = \frac{2\pi}{T_s}$.
- (b)(i) The function $\Pi(\frac{\Omega}{4\pi\times10^3})$ is equal to 1 if $-\frac{1}{2} < \frac{\Omega}{4\pi\times10^3} < \frac{1}{2} \Rightarrow -2\pi\times10^3 < \Omega < 2\pi\times10^3$, equal to $\frac{1}{2}$ if $\Omega = \pm 2\pi\times10^3$ and 0 otherwise. Therefore, $X(\Omega)$ has the form shown below.



Based on the sampling theorem (called also Nyquist criterion) the sampling frequency must be at twice the maximum frequency of the signal. In that case:

$$\Omega_s = 2\pi f_s \ge 2(2\pi \times 10^3) \Rightarrow f_s \ge 2 \times 10^3 \Rightarrow T_s = \frac{1}{f_s} \le 0.5 \times 10^{-3}$$

(ii) Based on the analysis given in the first section of this set of notes, the DTFT of x[n] has the form shown below. The horizontal axis ω is the axis Ω shown above, multiplied by $T_s = 10^{-4}$ sec



4.

(a) (i) The z transform expression is

$$X(z) = \sum_{n=1}^{+\infty} a^n z^{-n} = \sum_{n=0}^{+\infty} (az^{-1})^n - 1$$

If $\left|az^{-1}\right| < 1$, or equivalently, $\left|z\right| > \left|a\right|$, the above sum converges and

$$X(z) = \frac{1}{1 - az^{-1}} - 1 = \frac{z}{z - a} - 1 = \frac{a}{z - a}, |z| > |a|$$
$$x(n) = \begin{cases} -a^n & n < 0\\ 0 & n \ge 0 \end{cases}$$

(ii) The z transform expression is

$$X(z) = -\sum_{n=-\infty}^{0} a^n z^{-n} = -\sum_{n=0}^{+\infty} a^{-n} z^n$$

If $\left|a^{-1}z\right| < 1$, or equivalently, $\left|z\right| < \left|a\right|$, the above sum converges and

$$X(z) = -\frac{1}{1 - a^{-1}z} = \frac{a}{z - a}, |z| < |a|$$

(b)
$$y[n] - \frac{9}{2}y[n-1] + 2y[n-2] = -7x[n] \Rightarrow Y(z) - \frac{9}{2}z^{-1}Y(z) + 2z^{-2}Y(z) = -7X(z)$$

$$\Rightarrow H(z) = \frac{-7}{1 - \frac{9}{2}z^{-1} + 2z^{-2}} = \frac{1}{1 - \frac{1}{2}z^{-1}} - \frac{8}{1 - 4z^{-1}} \Rightarrow$$

$$h(n) = (\frac{1}{2})^n u[n] + 4^n u[n]$$

$$h(n) = (\frac{1}{2})^n u[n] - 4^n u[-n-1]$$

Nether causal nor stable

$$h(n) = -(\frac{1}{2})^n u[-n-1] + 4^n u[n]$$
 or

$$h(n) = -(\frac{1}{2})^n u[-n-1] - 4^n u[-n-1]$$