

MATHEMATICAL TRIPOS Part III

Thursday 2 June, 2005 1:30 to 4:30

PAPER 42

STATISTICAL THEORY

Attempt **FOUR** questions. There are **SIX** questions in total. The questions carry equal weight.

STATIONERY REQUIREMENTS Cover sheet Treasury Tag Script paper SPECIAL REQUIREMENTS
None

You may not start to read the questions printed on the subsequent pages until instructed to do so by the Invigilator. 2

1 Explain briefly the concepts of *profile likelihood* and *conditional likelihood*, for inference about a parameter of interest ψ , in the presence of a nuisance parameter λ .

Suppose Y_1, \ldots, Y_n are independent, identically distributed from the exponential family density

$$f(y;\psi,\lambda) = \exp\{\psi\tau_1(y) + \lambda\tau_2(y) - d(\psi,\lambda) - Q(y)\},\$$

where ψ, λ are both scalar.

Obtain a saddlepoint approximation to the density of $S = n^{-1} \sum_{i=1}^{n} \tau_2(Y_i)$.

Show that use of the saddle point approximation leads to an approximate conditional log-likelihood function for ψ of the form

$$l_p(\psi) + B(\psi),$$

where $l_p(\psi)$ is the profile log-likelihood, and $B(\psi)$ is an adjustment which you should specify carefully.

2 Explain in detail what is meant by a *transformation model*.

What is meant by (i) a *maximal invariant*, (ii) an *equivariant estimator*, in the context of a transformation model?

Describe in detail how an equivariant estimator can be used to construct a maximal invariant. Illustrate the construction for the case of a *location-scale* model.

Paper 42

3

3 Let Y_1, \ldots, Y_n be independent, identically distributed $N(\mu, \mu^2), \mu > 0$.

Show that this model is an example of a $\it curved$ $\it exponential$ $\it family,$ and find a minimal sufficient statistic.

Show that

$$a = \sqrt{n} \frac{(\sum Y_i^2)^{1/2}}{\sum Y_i}$$

is an ancillary statistic.

Assume that a > 0. Show that the maximum likelihood estimator of μ is

$$\hat{\mu} = \frac{(\sum Y_i^2)^{1/2}}{q\sqrt{n}},$$

where $q = \{(1+4a^2)^{1/2} + 1\}/(2a)$.

Show further that (apart from a constant) the log-likelihood may be written

$$l(\mu; \hat{\mu}, a) = -\frac{n}{2\mu^2} \left(q^2 \hat{\mu}^2 - \frac{2q\mu\hat{\mu}}{a} \right) - n\log\mu,$$

and obtain the p^* approximation to the (conditional) density of $\hat{\mu}$.

How would you approximate $\operatorname{Prob}(\hat{\mu} \leq t | a)$, for given t?

4 Explain what is meant by an *M*-estimator of a parameter θ , based on a given ψ function. Show that under appropriate conditions allowing the interchange of order of integration and differentiation, the influence function is proportional to ψ and derive an expression for the asymptotic variance $V(\psi, F)$ of the *M*-estimator at a distribution *F*.

A location model on \mathbb{R} , with parameter space \mathbb{R} , is specified by $F_{\theta}(x) = F(x - \theta)$, and an *M*-estimator is constructed using a ψ function of the form $\psi(x, \theta) = \psi(x - \theta)$.

For the particular choice

$$\psi(x) = \min\{b, \max\{x, -b\}\}, \quad b < \infty :$$

(i) Find the asymptotic variance $V(\psi, \Phi)$, where Φ is the standard normal distribution;

(ii) Verify that the estimator is B-robust, by determining an explicit bound on the influence function.

Paper 42

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5 Let Y_1, \ldots, Y_n be independent, identically distributed from a distribution F, with density f symmetric about an unknown point θ . Suppose we wish to test $H_0: \theta = \theta_0$ against $H_1: \theta < \theta_0$.

Explain how to test H_0 against H_1 using (i) the sign test, and (ii) the Wilcoxon signed rank test.

Show that the null mean and variance of the Wilcoxon signed rank statistic are $\frac{1}{4}n(n+1)$ and $\frac{1}{24}n(n+1)(2n+1)$ respectively.

What is meant by a one-sample U-statistic?

State, without proof, a result concerning the asymptotic distribution of a one-sample U-statistic, and use it to deduce asymptotic normality of the Wilcoxon signed rank statistic.

6 Write brief notes on *four* of the following:

- (i) Edgeworth expansion;
- (ii) parameter orthogonality;
- (iii) Laplace approximation;
- (iv) Bartlett correction;
- (v) the invariance principle;
- (vi) finite-sample versions of robustness measures;
- (vii) tests based on the empirical distribution function;
- (viii) large-sample likelihood theory.

END OF PAPER