

MATHEMATICAL TRIPOS Part III

Tuesday 7 June, 2005 9 to 12

PAPER 15

DIFFERENTIAL GEOMETRY

Attempt **THREE** questions.

There are **FIVE** questions in total.

The questions carry equal weight.

All manifolds and related concepts should be assumed to be smooth.

STATIONERY REQUIREMENTS

Cover sheet
Treasury Tag
Script paper

SPECIAL REQUIREMENTS

None

<p>You may not start to read the questions printed on the subsequent pages until instructed to do so by the Invigilator.</p>
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1 State the defining properties of the exterior derivative d for the differential forms on a manifold M and show that d exists and is uniquely determined. Show also that $d\omega(X, Y) = X\omega(Y) - Y\omega(X) - \omega([X, Y])$, for any vector fields X, Y and any differential 1-form ω on M .

Define the de Rham cohomology groups and state Poincaré lemma. For any $n > 1$, show that there is an injective linear map $H^n(S^n) \rightarrow H^{n-1}(S^{n-1})$ between de Rham cohomology groups of spheres.

2 Define the concept of an embedded submanifold.

Let $f : M \rightarrow N$ be a smooth map between manifolds M and N . Define the regular values of f and prove that if $q \in N$ is a regular value of f then $f^{-1}(q)$ is an embedded submanifold of M of dimension $\dim M - \dim N$. [*You need not give a proof of the Inverse Mapping Theorem between open domains in a Euclidean space but should include an accurate statement.*]

State three different equivalent formulations of orientability for a manifold. Now let q be a regular value of $f : M \rightarrow N$ as above and assume that the manifold M is orientable. Deduce that the manifold $f^{-1}(q)$ is orientable too.

3 Show that an orthogonal structure on a real vector bundle E is equivalent to a choice of an inner product on E . Explain what is meant by an orthogonal local trivialization. Show that any real vector bundle admits an inner product.

Give two different ways to define the notion of orthogonal connection A on E , relative to an inner product h , and prove that these two definitions are equivalent.

[*Existence of a partition of unity on a manifold can be assumed without proof provided the result is accurately stated. You may assume without proof that every covariant derivative arises from a connection.*]

4 Let V be a Riemannian manifold and M an embedded submanifold of V . State the Gauss formula relating the Levi-Civita connections on V and on M . State the Weingarten formula defining the shape operator on M and prove that the shape operator is symmetric (self-adjoint).

State and prove the Gauss theorem for the curvature of the metric on M induced from V . Explain how the latter result implies Gauss' *Theorema Egregium*.

[*You may use without proof the formula $R(X, Y) = D_{[X, Y]} - [D_X, D_Y]$ for the curvature operator.*]

5 Let M be a compact oriented manifold endowed with a Riemannian metric g . Explain what is meant by the volume form of g showing that this volume form is well-defined. Define the Hodge $*$ -operator. Identify, giving justification, all the complex numbers which occur as the eigenvalues of $*$.

Recall that the Laplace–Beltrami operator for the differential forms on M is defined by $\Delta = d\delta + \delta d$, where $\delta\eta = (-1)^{n(r+1)+1} *d*\eta$, for a form η of degree $r \geq 1$ ($n = \dim M$), and $\delta f = 0$ for a function f . Show that δ is the formal adjoint of d with respect to the L^2 inner product. State the Hodge decomposition theorem and give a necessary and sufficient condition on a differential form $\beta \in \Omega^k(M)$ so that the equation $\Delta\alpha = \beta$ has solutions $\alpha \in \Omega^k(M)$. Show that the set of all solutions α (if they exist) forms an affine space with the underlying vector space isomorphic to the de Rham cohomology $H^k(M)$.

[Standard results on the integration of differential n -forms on an n -dimensional manifold can be used without proof provided that these are clearly stated.]

END OF PAPER