

MATHEMATICAL TRIPOS      Part IA

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Tuesday 5th June 2007    1.30 pm to 4.30 pm

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**PAPER 3**

**Before you begin read these instructions carefully.**

*The examination paper is divided into two sections. Each question in Section II carries twice the number of marks of each question in Section I. Candidates may attempt **all four** questions from Section I and **at most five** questions from Section II. In Section II, no more than **three** questions on each course may be attempted.*

***Complete answers are preferred to fragments.***

*Write on **one** side of the paper only and begin each answer on a separate sheet.*

*Write legibly; otherwise you place yourself at a grave disadvantage.*

**At the end of the examination:**

*Tie up your answers in separate bundles, marked **A** and **D** according to the code letter affixed to each question. Include in the same bundle all questions from Section I and II with the same code letter.*

*Attach a gold cover sheet to each bundle; write the code letter in the box marked 'EXAMINER LETTER' on the cover sheet.*

*You must also complete a green master cover sheet listing all the questions you have attempted.*

***Every cover sheet must bear your examination number and desk number.***

**STATIONERY REQUIREMENTS**

*Gold cover sheet*

*Green master cover sheet*

**SPECIAL REQUIREMENTS**

*None*

<p><b>You may not start to read the questions printed on the subsequent pages until instructed to do so by the Invigilator.</b></p>
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## SECTION I

### 1D Algebra and Geometry

Prove that every permutation of  $\{1, \dots, n\}$  may be expressed as a product of disjoint cycles.

Let  $\sigma = (1234)$  and let  $\tau = (345)(678)$ . Write  $\sigma\tau$  as a product of disjoint cycles. What is the order of  $\sigma\tau$ ?

### 2D Algebra and Geometry

What does it mean to say that groups  $G$  and  $H$  are *isomorphic*?

Prove that no two of  $C_8$ ,  $C_4 \times C_2$  and  $C_2 \times C_2 \times C_2$  are isomorphic. [Here  $C_n$  denotes the cyclic group of order  $n$ .]

Give, with justification, a group of order 8 that is not isomorphic to any of those three groups.

### 3A Vector Calculus

(i) Give definitions for the unit tangent vector  $\hat{\mathbf{T}}$  and the curvature  $\kappa$  of a parametrised curve  $\mathbf{x}(t)$  in  $\mathbb{R}^3$ . Calculate  $\hat{\mathbf{T}}$  and  $\kappa$  for the circular helix

$$\mathbf{x}(t) = (a \cos t, a \sin t, bt),$$

where  $a$  and  $b$  are constants.

(ii) Find the normal vector and the equation of the tangent plane to the surface  $S$  in  $\mathbb{R}^3$  given by

$$z = x^2y^3 - y + 1$$

at the point  $x = 1, y = 1, z = 1$ .

### 4A Vector Calculus

By using suffix notation, prove the following identities for the vector fields  $\mathbf{A}$  and  $\mathbf{B}$  in  $\mathbb{R}^3$ :

$$\nabla \cdot (\mathbf{A} \times \mathbf{B}) = \mathbf{B} \cdot (\nabla \times \mathbf{A}) - \mathbf{A} \cdot (\nabla \times \mathbf{B});$$

$$\nabla \times (\mathbf{A} \times \mathbf{B}) = (\mathbf{B} \cdot \nabla)\mathbf{A} - \mathbf{B}(\nabla \cdot \mathbf{A}) - (\mathbf{A} \cdot \nabla)\mathbf{B} + \mathbf{A}(\nabla \cdot \mathbf{B}).$$

## SECTION II

### 5D Algebra and Geometry

Let  $x$  be an element of a finite group  $G$ . What is meant by the *order* of  $x$ ? Prove that the order of  $x$  must divide the order of  $G$ . [*No version of Lagrange's theorem or the Orbit-Stabilizer theorem may be used without proof.*]

If  $G$  is a group of order  $n$ , and  $d$  is a divisor of  $n$  with  $d < n$ , is it always true that  $G$  must contain an element of order  $d$ ? Justify your answer.

Prove that if  $m$  and  $n$  are coprime then the group  $C_m \times C_n$  is cyclic.

If  $m$  and  $n$  are not coprime, can it happen that  $C_m \times C_n$  is cyclic?

[Here  $C_n$  denotes the cyclic group of order  $n$ .]

### 6D Algebra and Geometry

What does it mean to say that a subgroup  $H$  of a group  $G$  is *normal*? Give, with justification, an example of a subgroup of a group that is normal, and also an example of a subgroup of a group that is not normal.

If  $H$  is a normal subgroup of  $G$ , explain carefully how to make the set of (left) cosets of  $H$  into a group.

Let  $H$  be a normal subgroup of a finite group  $G$ . Which of the following are always true, and which can be false? Give proofs or counterexamples as appropriate.

- (i) If  $G$  is cyclic then  $H$  and  $G/H$  are cyclic.
- (ii) If  $H$  and  $G/H$  are cyclic then  $G$  is cyclic.
- (iii) If  $G$  is abelian then  $H$  and  $G/H$  are abelian.
- (iv) If  $H$  and  $G/H$  are abelian then  $G$  is abelian.

### 7D Algebra and Geometry

Let  $A$  be a real symmetric  $n \times n$  matrix. Prove that every eigenvalue of  $A$  is real, and that eigenvectors corresponding to distinct eigenvalues are orthogonal. Indicate clearly where in your argument you have used the fact that  $A$  is real.

What does it mean to say that a real  $n \times n$  matrix  $P$  is *orthogonal*? Show that if  $P$  is orthogonal and  $A$  is as above then  $P^{-1}AP$  is symmetric. If  $P$  is any real invertible matrix, must  $P^{-1}AP$  be symmetric? Justify your answer.

Give, with justification, real  $2 \times 2$  matrices  $B, C, D, E$  with the following properties:

- (i)  $B$  has no real eigenvalues;
- (ii)  $C$  is not diagonalisable over  $\mathbb{C}$ ;
- (iii)  $D$  is diagonalisable over  $\mathbb{C}$ , but not over  $\mathbb{R}$ ;
- (iv)  $E$  is diagonalisable over  $\mathbb{R}$ , but does not have an orthonormal basis of eigenvectors.

### 8D Algebra and Geometry

In the group of Möbius maps, what is the order of the Möbius map  $z \mapsto \frac{1}{z}$ ? What is the order of the Möbius map  $z \mapsto \frac{1}{1-z}$ ?

Prove that every Möbius map is conjugate either to a map of the form  $z \mapsto \mu z$  (some  $\mu \in \mathbb{C}$ ) or to the map  $z \mapsto z + 1$ . Is  $z \mapsto z + 1$  conjugate to a map of the form  $z \mapsto \mu z$ ?

Let  $f$  be a Möbius map of order  $n$ , for some positive integer  $n$ . Under the action on  $\mathbb{C} \cup \{\infty\}$  of the group generated by  $f$ , what are the various sizes of the orbits? Justify your answer.

**9A Vector Calculus**

(i) Define what is meant by a conservative vector field. Given a vector field  $\mathbf{A} = (A_1(x, y), A_2(x, y))$  and a function  $\psi(x, y)$  defined in  $\mathbb{R}^2$ , show that, if  $\psi\mathbf{A}$  is a conservative vector field, then

$$\psi \left( \frac{\partial A_1}{\partial y} - \frac{\partial A_2}{\partial x} \right) = A_2 \frac{\partial \psi}{\partial x} - A_1 \frac{\partial \psi}{\partial y}.$$

(ii) Given two functions  $P(x, y)$  and  $Q(x, y)$  defined in  $\mathbb{R}^2$ , prove Green's theorem,

$$\oint_C (P dx + Q dy) = \iint_R \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy,$$

where  $C$  is a simple closed curve bounding a region  $R$  in  $\mathbb{R}^2$ .

Through an appropriate choice for  $P$  and  $Q$ , find an expression for the area of the region  $R$ , and apply this to evaluate the area of the ellipse bounded by the curve

$$x = a \cos \theta, \quad y = b \sin \theta, \quad 0 \leq \theta \leq 2\pi.$$

### 10A Vector Calculus

For a given charge distribution  $\rho(x, y, z)$  and divergence-free current distribution  $\mathbf{J}(x, y, z)$  (i.e.  $\nabla \cdot \mathbf{J} = 0$ ) in  $\mathbb{R}^3$ , the electric and magnetic fields  $\mathbf{E}(x, y, z)$  and  $\mathbf{B}(x, y, z)$  satisfy the equations

$$\nabla \times \mathbf{E} = 0, \quad \nabla \cdot \mathbf{B} = 0, \quad \nabla \cdot \mathbf{E} = \rho, \quad \nabla \times \mathbf{B} = \mathbf{J}.$$

The radiation flux vector  $\mathbf{P}$  is defined by  $\mathbf{P} = \mathbf{E} \times \mathbf{B}$ .

For a closed surface  $S$  around a region  $V$ , show using Gauss' theorem that the flux of the vector  $\mathbf{P}$  through  $S$  can be expressed as

$$\iint_S \mathbf{P} \cdot d\mathbf{S} = - \iiint_V \mathbf{E} \cdot \mathbf{J} dV. \quad (*)$$

For electric and magnetic fields given by

$$\mathbf{E}(x, y, z) = (z, 0, x), \quad \mathbf{B}(x, y, z) = (0, -xy, xz),$$

find the radiation flux through the quadrant of the unit spherical shell given by

$$x^2 + y^2 + z^2 = 1, \quad \text{with } 0 \leq x \leq 1, \quad 0 \leq y \leq 1, \quad -1 \leq z \leq 1.$$

[If you use (\*), note that an open surface has been specified.]

### 11A Vector Calculus

The function  $\phi(x, y, z)$  satisfies  $\nabla^2\phi = 0$  in  $V$  and  $\phi = 0$  on  $S$ , where  $V$  is a region of  $\mathbb{R}^3$  which is bounded by the surface  $S$ . Prove that  $\phi = 0$  everywhere in  $V$ .

Deduce that there is at most one function  $\psi(x, y, z)$  satisfying  $\nabla^2\psi = \rho$  in  $V$  and  $\psi = f$  on  $S$ , where  $\rho(x, y, z)$  and  $f(x, y, z)$  are given functions.

Given that the function  $\psi = \psi(r)$  depends only on the radial coordinate  $r = |\mathbf{x}|$ , use Cartesian coordinates to show that

$$\nabla\psi = \frac{1}{r} \frac{d\psi}{dr} \mathbf{x}, \quad \nabla^2\psi = \frac{1}{r} \frac{d^2(r\psi)}{dr^2}.$$

Find the general solution in this radial case for  $\nabla^2\psi = c$  where  $c$  is a constant.

Find solutions  $\psi(r)$  for a solid sphere of radius  $r = 2$  with a central cavity of radius  $r = 1$  in the following three regions:

- (i)  $0 \leq r \leq 1$  where  $\nabla^2\psi = 0$  and  $\psi(1) = 1$  and  $\psi$  bounded as  $r \rightarrow 0$ ;
- (ii)  $1 \leq r \leq 2$  where  $\nabla^2\psi = 1$  and  $\psi(1) = \psi(2) = 1$ ;
- (iii)  $r \geq 2$  where  $\nabla^2\psi = 0$  and  $\psi(2) = 1$  and  $\psi \rightarrow 0$  as  $r \rightarrow \infty$ .

### 12A Vector Calculus

Show that any second rank Cartesian tensor  $P_{ij}$  in  $\mathbb{R}^3$  can be written as a sum of a symmetric tensor and an antisymmetric tensor. Further, show that  $P_{ij}$  can be decomposed into the following terms

$$P_{ij} = P\delta_{ij} + S_{ij} + \epsilon_{ijk}A_k, \quad (\dagger)$$

where  $S_{ij}$  is symmetric and traceless. Give expressions for  $P$ ,  $S_{ij}$  and  $A_k$  explicitly in terms of  $P_{ij}$ .

For an isotropic material, the stress  $P_{ij}$  can be related to the strain  $T_{ij}$  through the stress-strain relation,  $P_{ij} = c_{ijkl}T_{kl}$ , where the elasticity tensor is given by

$$c_{ijkl} = \alpha\delta_{ij}\delta_{kl} + \beta\delta_{ik}\delta_{jl} + \gamma\delta_{il}\delta_{jk}$$

and  $\alpha$ ,  $\beta$  and  $\gamma$  are scalars. As in  $(\dagger)$ , the strain  $T_{ij}$  can be decomposed into its trace  $T$ , a symmetric traceless tensor  $W_{ij}$  and a vector  $V_k$ . Use the stress-strain relation to express each of  $T$ ,  $W_{ij}$  and  $V_k$  in terms of  $P$ ,  $S_{ij}$  and  $A_k$ .

Hence, or otherwise, show that if  $T_{ij}$  is symmetric then so is  $P_{ij}$ . Show also that the stress-strain relation can be written in the form

$$P_{ij} = \lambda\delta_{ij}T_{kk} + \mu T_{ij},$$

where  $\mu$  and  $\lambda$  are scalars.

**END OF PAPER**