

# **2010 Technological Studies**

### Standard Grade – General

# **Finalised Marking Instructions**

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rocontrollers consist of several sub-systems. Complete the table by matching the correct sub-system from the list below with its function given in the table. ALU Clock RAM Bus ROM Microcontroller       RAM       Bus       ROM         Microcontroller       Synchronises the system and controls the speed of operation.       Image: Clock       Synchronises the system and controls the speed of operation.       5         ALU       The "brain" of the microcontroller that carries out mathematical functions.       5       3         Bus       Used to move information between microcontroller sub-systems.       5       3         ROM       Permanent memory where a program can be stored.       5       3         State the full name of the following microcontroller sub-systems.       1       1         (ii)       RAM       remory       0       1         (iii)       RAM       Immore memory       1       1         (iii)       ALU       Andom access memory       1       1			Mark Allocation	Ma	arks
notative Synchronises the sub-systems.   ALU Clock   RAM Bus   RAM Bus   RAM Bus   RAM Clock   Synchronises the system and controls the speed of operation.   ALU Clock   Synchronises the system and controls the speed of operation.   ALU The "brain" of the microcontroller that carries out mathematical functions.   Bus Used to move information between microcontroller sub-systems.   RAM Temporary memory used during the running of the program/task.   ROM Permanent memory where a program can be stored.				KU	RNA
ALU       Clock       RAM       Bus       ROM         Microcontroller       Function       Function       Function         sub-systems       Synchronises the system and controls the speed of operation.       Operation.       Function       Function	Complete the table from the list below	of several sub-sy e by matching the v with its function	e correct sub-system n given in the table.		
Microcontroller       Function         sub-systems       Clock       Synchronises the system and controls the speed of operation.         ALU       The "brain" of the microcontroller that carries out mathematical functions.         Bus       Used to move information between microcontroller sub-systems.         RAM       Temporary memory used during the running of the program/task.         ROM       Permanent memory where a program can be stored.         State the full name of the following microcontroller sub-systems.       10         (i)       ROM         Full name       Read only memory         (ii)       RAM         Full name       Random access memory         (iii)       ALU         Full name       Arithmetic logic unit         10       10	ALU C	lock RA	AM Bus ROM		
sub-systems	Microco	ontroller	Function		
Clock       Synchronises the system and controls the speed of operation.         ALU       The "brain" of the microcontroller that carries out mathematical functions.         Bus       Used to move information between microcontroller sub-systems.         RAM       Temporary memory used during the running of the program/task.         ROM       Permanent memory where a program can be stored.         State the full name of the following microcontroller sub-systems.       1         (i)       ROM         Full name       Read only memory         (ii)       RAM         Full name       Random access memory         (iii)       ALU         Full name       Arithmetic logic unit         1       0	sub-sy	vstems			
ALU       The "brain" of the microcontroller that carries out mathematical functions.         Bus       Used to move information between microcontroller sub-systems.         RAM       Temporary memory used during the running of the program/task.         ROM       Permanent memory where a program can be stored.         State the full name of the following microcontroller sub-systems.       1         (i)       ROM         Full name       Read only memory         (ii)       RAM         Full name       Random access memory         (iii)       ALU         Full name       Arithmetic logic unit         1       0		ock	Synchronises the system and controls the speed of operation.		
Bus     Used to move information between microcontroller sub-systems.     5       RAM     Temporary memory used during the running of the program/task.     5       ROM     Permanent memory where a program can be stored.     0       State the full name of the following microcontroller sub-systems.     0       (i)     ROM     1       Full name     Read only memory     0       (ii)     RAM     1       Full name     Random access memory     0       (iii)     ALU     1       Full name     Arithmetic logic unit     1	AI	LU	The "brain" of the microcontroller that carries out mathematical functions.		
RAM       Temporary memory used during the running of the program/task.       3         ROM       Permanent memory where a program can be stored.       1         State the full name of the following microcontroller sub-systems.       1       0         (i)       ROM       Full name       1       0         (ii)       RAM       Full name       1       0         (iii)       RAM       1       0       1         (iii)       ALU       Full name       Arithmetic logic unit       1       0         (iiii)       ALU       Full name       Arithmetic logic unit       1       0	Bi	us	Used to move information between microcontroller sub-systems.	F	
ROM       Permanent memory where a program can be stored.       2         State the full name of the following microcontroller sub-systems.       1         (i)       ROM       1         Full name       Read only memory       1         (ii)       RAM       1         Full name       Random access memory       1         (iii)       ALU       1         Full name       Arithmetic logic unit       1	RA	M	Temporary memory used during the running of the program/task.	5 4 3	
State the full name of the following microcontroller sub-systems.       1         (i)       ROM         Full name       Read only memory         (ii)       RAM         Full name       Random access memory         (iii)       ALU         Full name       Arithmetic logic unit         1       0	RC	)M	Permanent memory where a program can be stored.	2 1 0	
	<ul> <li>(i) ROM</li> <li>Full name</li> <li>(ii) RAM</li> <li>Full name</li> <li>(iii) ALU</li> <li>Full name</li> </ul>	Read only mo	emory ess memory ogic unit	1 0 1 0	

1.



			KU	ŀ
An automatic sliding roof for a spor	ts stadium is operated	by a microcontroller.		
	A SHOLEN A			
		A A A		
	the state of the			
	1-			
	A. A. C. T.			
		and the second s		
	1.75			
	VYY C			
		I A State State		
	TELEN BAT			
Part of the control program includes	a sub-procedure 'clos	se' which will run when frost is		
detected.	*			
The sequence is as follows:				
<ul> <li>after a 5 second delay the roof n</li> </ul>	notor switches on;			
<ul> <li>after a 5 second delay the roof n</li> <li>when the stadium roof is fully cl</li> </ul>	notor switches on; losed a limit switch is	activated which stops the motor;		
<ul> <li>after a 5 second delay the roof n</li> <li>when the stadium roof is fully cl</li> <li>the sequence ends and returns to</li> </ul>	notor switches on; losed a limit switch is o the main program.	activated which stops the motor;		
<ul> <li>after a 5 second delay the roof n</li> <li>when the stadium roof is fully cl</li> <li>the sequence ends and returns to</li> </ul>	notor switches on; losed a limit switch is the main program.	activated which stops the motor;		
<ul> <li>after a 5 second delay the roof n</li> <li>when the stadium roof is fully ci</li> <li>the sequence ends and returns to</li> <li>INPUT</li> </ul>	notor switches on; losed a limit switch is the main program. COUTPUT CONNE Pin	activated which stops the motor; CTIONS Output Connection		
<ul> <li>after a 5 second delay the roof n</li> <li>when the stadium roof is fully c.</li> <li>the sequence ends and returns to</li> <li>INPUT</li> </ul>	notor switches on; losed a limit switch is the main program. <b>COUTPUT CONNE</b> <b>Pin</b> 7	activated which stops the motor; CTIONS Output Connection		
<ul> <li>after a 5 second delay the roof n</li> <li>when the stadium roof is fully c.</li> <li>the sequence ends and returns to</li> <li>INPUT</li> </ul>	notor switches on; losed a limit switch is the main program. <b>COUTPUT CONNE</b> <b>Pin</b> 7 6	activated which stops the motor; CTIONS Output Connection Roof motor		
<ul> <li>after a 5 second delay the roof n</li> <li>when the stadium roof is fully c.</li> <li>the sequence ends and returns to</li> <li>INPUT</li> </ul>	notor switches on; losed a limit switch is the main program. <b>E/OUTPUT CONNE</b> <b>Pin</b> 7 6 5	activated which stops the motor; CTIONS Output Connection Roof motor		
<ul> <li>after a 5 second delay the roof n</li> <li>when the stadium roof is fully c.</li> <li>the sequence ends and returns to</li> <li>INPUT</li> </ul>	hotor switches on; losed a limit switch is the main program. <b>E/OUTPUT CONNE</b> <b>Pin</b> 7 6 5 4	activated which stops the motor; CTIONS Output Connection Roof motor Floodlights		
<ul> <li>after a 5 second delay the roof n</li> <li>when the stadium roof is fully c.</li> <li>the sequence ends and returns to</li> <li>INPUT</li> </ul>	hotor switches on; losed a limit switch is the main program. <b>FOUTPUT CONNE</b> <b>Pin</b> 7 6 5 4 3	activated which stops the motor; CTIONS Output Connection Roof motor Floodlights		
<ul> <li>after a 5 second delay the roof n</li> <li>when the stadium roof is fully c.</li> <li>the sequence ends and returns to</li> <li>INPUT</li> </ul>	notor switches on; losed a limit switch is the main program. <b>FOUTPUT CONNE</b> <b>Pin</b> 7 6 5 4 3 2	activated which stops the motor; CTIONS Output Connection Roof motor Floodlights		
<ul> <li>The modulights switch on;</li> <li>after a 5 second delay the roof n</li> <li>when the stadium roof is fully cited the sequence ends and returns to INPUT</li> <li>Input Connection</li> <li>Limit Switch</li> </ul>	notor switches on; losed a limit switch is the main program. <b>FOUTPUT CONNE</b> <b>Pin</b> 7 6 5 4 3 2 1	activated which stops the motor; CTIONS Output Connection Roof motor Floodlights		
after a 5 second delay the roof n     when the stadium roof is fully c     the sequence ends and returns to         INPUT         Input Connection         Limit Switch	hotor switches on; losed a limit switch is the main program. <b>FOUTPUT CONNE</b> <b>Pin</b> 7 6 5 4 3 2 1 0	activated which stops the motor; CTIONS Output Connection Roof motor Floodlights		
Ine moonghts switch on;     after a 5 second delay the roof n     when the stadium roof is fully c     the sequence ends and returns to         INPUT         Input Connection         Limit Switch	Pin 7 6 7 6 5 4 3 2 1 0	activated which stops the motor; CTIONS Output Connection Roof motor Floodlights		
Ine moonghts switch on;     after a 5 second delay the roof n     when the stadium roof is fully c     the sequence ends and returns to         INPUT         Input Connection         Limit Switch	Pin 7 6 7 6 5 4 3 2 1 0	activated which stops the motor; CTIONS           Output Connection           Roof motor           Floodlights		

### Marks KU RNA 3. (continued) Complete, with reference to the sequence of operations and Data Booklet, the flowchart *(a)* for sub-procedures 'close'. Close Floodlights -1 RNA On High 4 Pause 5000 Wait 5 - 1 RNA Seconds 1 RNA-Roof Motor High 6 On - 1 RNA 1 RNA -Statement Limit Switch Ν Closed? Y 1 RNA -Roof Motor Low 6 Off 7 **1 RNA for correct** 6 symbols (all) 5 4 3 2 Return 1 0











The diagram below shows the forces and distances on the skateboard.



(a) State the name given to the type of diagram shown above.

#### Free body (diagram)

(b) (i) Calculate, by taking moments about  $R_2$ , the size of the reaction force  $R_1$ .

$$\begin{split} \Sigma CWM &= \Sigma ACWM \\ (R_1 \times 500) &= (500 \times 350) \\ R_1 &= \frac{500 \times 350}{500} \\ R_1 &= 350 \text{ N} \end{split} \begin{array}{c} 1 \text{ RNA for substituion} \\ 1 \text{ RNA for transposition} \\ 1 \text{ RNA for correct answer from given working} \\ \end{split}$$

(ii) Calculate the reaction force  $R_2$ .

	$\Sigma$ downward	=	$\Sigma$ upward
1 RNA for substituion – FTE	500	=	$350 + R_2$
	500 - 350	=	$R_2$
1 RNA for correct answer from			
given working	150 N	=	$R_2$

Bearings are used in the wheels of a skateboard to reduce friction.

(c) State **one** other method which can be used to reduce friction.





1 0

Marks

RNA

KU

2 1 0

3

Marks KU RNA A hire shop in a popular Spanish resort rents out electric scooters. 7. The scooters use rechargeable batteries. *(a)* Part of a resistor arrangement for the battery charger is shown. O  $2 \cdot 2 \Omega$ -0 2Ω (i) Calculate the resistance of the **parallel** branch shown above.  $\frac{\mathbf{R}_1 \times \mathbf{R}_2}{\mathbf{R}_1 + \mathbf{R}_2}$ R<sub>T</sub>  $\frac{6 \times 2}{6+2}$ = 2 1  $\frac{12}{8} = 1.5 \ \Omega$ **1 RNA for substitution** = 1 RNA for correct answer from given working 0 Calculate the total circuit resistance for the arrangement shown above. (ii)  $\begin{array}{c} R_1+R_2\\ 2{\cdot}2+1{\cdot}5 \end{array}$ FTE 2 R<sub>T</sub> = = **1 RNA for substitution** 1 3·7 Ω 1 RNA for correct answer from given working 0 = Other electronic components are used in the battery charger. State the name of the electronic components shown below. *(b)* 3 2 1 2 Diode 3 Transistor 0 1 **LED** 



	Poir	nt B	Point A		
(a)	Calculate the potential ener	gy of the snowboarder at poin	nt A.		
	PE = mgh = $65 \times 9.81 \times$ = $3825.9 J$	< 6 1 RNA for corr	1 RNA for substitution rect answer from given working		2 1 0
The	snowboarder is travelling at 1	10 m/s when he reaches point	В.		
(1)	Calculate the kinetic energy	of the snowboarder at point	B.		
( <i>b</i> )					
(b) (c)	$KE = \frac{\frac{1}{2} \text{ mv}^2}{= 0.5 \times 65 \times}$ $= 3250 \text{ J}$ Complete the table below to or non-renewable.	$10^2$ <b>1 RNA for corr</b> to indicate ( $\checkmark$ ) whether each li	1 RNA for substitution rect answer from given working isted energy source is renewable		2 1 0
(b) (c)	$KE = \frac{1/2}{2} mv^{2}$ $= 0.5 \times 65 \times$ $= 3250 J$ Complete the table below to or non-renewable.	10 <sup>2</sup> <b>1 RNA for corr</b> to indicate (✓) whether each li Ener	<b>1 RNA for substitution</b> <b>rect answer from given working</b> isted energy source is renewable		2 1 0
(b) (c)	$KE = \frac{\frac{1}{2} \text{ mv}^2}{= 0.5 \times 65 \times}$ $= 3250 \text{ J}$ Complete the table below to or non-renewable. Energy source	$10^{2}$ <b>1 RNA for corr</b> to indicate ( $\checkmark$ ) whether each lite Enerr <i>Renewable</i>	1 RNA for substitution         rect answer from given working         isted energy source is renewable         rgy type         Non-renewable		2 1 0
( <i>b</i> )	$KE = \frac{\frac{1}{2} \text{ mv}^2}{2 \text{ mv}^2}$ $= 0.5 \times 65 \times 250 \text{ J}$ Complete the table below to or non-renewable. Energy source	$10^{2}$ <b>1 RNA for corr</b> to indicate ( $\checkmark$ ) whether each line	1 RNA for substitution         rect answer from given working         isted energy source is renewable         rgy type         Non-renewable		2 1 0
( <i>b</i> )	$KE = \frac{\frac{1}{2} \text{ mv}^2}{2 \text{ mv}^2}$ $= 0.5 \times 65 \times 250 \text{ J}$ Complete the table below to or non-renewable. Energy source Wind Coal	$10^2$ <b>1 RNA for corr</b> to indicate ( $\checkmark$ ) whether each lite Energy Renewable $\checkmark$	1 RNA for substitution         rect answer from given working         isted energy source is renewable         rgy type         Non-renewable         √	5	2 1 0
( <i>b</i> )	$KE = \frac{\frac{1}{2} \text{mv}^2}{2 \text{mv}^2}$ $= 0.5 \times 65 \times 250 \text{ J}$ Complete the table below to or non-renewable. Energy source Wind Coal Gas	$10^{2}$ <b>1 RNA for corr</b> to indicate ( $\checkmark$ ) whether each lite Enerr <i>Renewable</i>	1 RNA for substitution         rect answer from given working         isted energy source is renewable         rgy type         Non-renewable         Image:	543	2 1 0
( <i>b</i> )	$KE = \frac{\frac{1}{2} \text{mv}^2}{2}$ $= 0.5 \times 65 \times 23250 \text{ J}$ Complete the table below to or non-renewable. Energy source Wind Coal Gas Bio-mass	$10^2$ <b>1 RNA for corr</b> to indicate ( $\checkmark$ ) whether each lis Ener Renewable $\checkmark$	1 RNA for substitution         rect answer from given working         isted energy source is renewable         rgy type         Non-renewable         Image:	5 4 3 2	2 1 0
( <i>b</i> )	$KE = \frac{\frac{1}{2} \text{mv}^2}{2 \text{mv}^2}$ $= 0.5 \times 65 \times 200 \text{ J}$ Complete the table below to or non-renewable. Energy source Wind Coal Gas Bio-mass Wave	$10^2$ <b>1 RNA for corr</b> to indicate ( $\checkmark$ ) whether each line	1 RNA for substitution         rect answer from given working         isted energy source is renewable         rgy type         Non-renewable         ✓         ✓         ✓         ✓         ✓	5 4 3 2 1 0	2 1 0

### [END OF MARKING INSTRUCTIONS]