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General Certificate of Secondary Education 2011

Technology and Design

Unit 2: Systems and Control

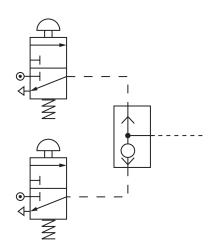
Element 2: Mechanical and Pneumatic Control Systems

[GTD22]

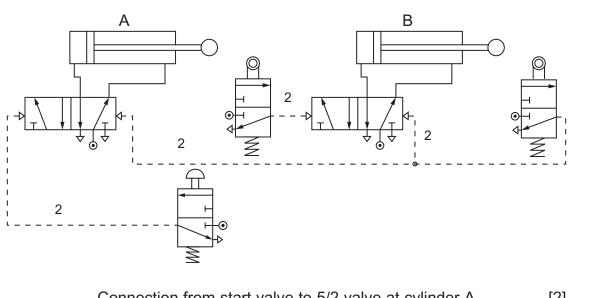
MONDAY 6 JUNE, MORNING

MARK SCHEME

Element 2				AVAILABLE MARKS	
Mechanical and Pneumatic Control Systems					
(a)	(i)	Double acting cylinder	[1]		
	(ii)	$F = P \times A$ 300 = 0.6 × A A = 300/0.6 = 500 mm ² Piston Area = 500 + 100 = 600 mm ²	[1] [1] [1] [2]		
(b)	(i)	A 3/2 valve B 5/2 valve C Reservoir D One way flow restrictor or Flow control valve	[4]		
	(ii)	Signal to switch 5/2 valve B , cylinder outstrokes slowly 3/2 roller valve F operated – time delay Valve B reset, cylinder instrokes .	[2] [2] [2]		
	(iii)	Adjust flow control valve E Change the position of valve F	[3] [3]		
	(iv)	Additional 3/2 start valve Shuttle valve Correct piping for shuttle valve	[2] [2] [2]		



1



Connection from start value to 5/2 value at cylinder A	[2]
Signal from 3/2 roller valve at A+ to 5/2 valve at cylinder	B [2]
Signal from 3/2 roller valve at B+ to 5/2 valve at cylinder	A [2]
Signal from 3/2 roller valve at B+ to 5/2 valve at cylinder	B [2]

(ii) Insert 3/2 roller valve at B– Connect signal from this valve to supply port of start valve

40

[2] [2] AVAILABLE MARKS

2 (a) Solutions

(b)

Sol	utions			AVAILABLE MARKS
	Name	Function		
	Ratchet and Pawl	В		
	Worm and wormwheel	D		
	Compound gear train	Α		
	Bell crank lever	С		
			8 × 1 [8]	
(i)	The load transmitted The distance between Is an exact speed ration re Can the transmission slip i Any two appropriate factor	f overloaded etc	2×2 [4]	
(ii)	belts Gears Chains <i>any two</i>		2×2 [4]	
(iii)	 Gears Advantages: large loads, exact speed ratios etc 1 off Disadvantage: lubrication required, short distance etc 1 off Belts Advantages: large distance, slip on overload, no lubrication etc 1 off Disadvantage: inexact ratios unless toothed, noisy etc 1 off Chains Advantages: large loads, large distance, exact ratios 1 off Disadvantage: noisy, lubrication required etc 1 off Any two of the above methods 			

(c)	(i)	Rack and pinion		[2]	AVAILABLE MARKS
	(ii)	Input – Rotary Output – Linear		[2] [2]	
	(iii)	Bore hole in handle and attach lever using adhesive. or Bore hole in handle, thread hole and end of lever.			
		Screw on handle		[4]	
	(iv)) Effort distance = $\Pi \times D/4$			
			$=\Pi imes$ 600/4	[2]	
			= 471.2	[2]	
		Drill distance	$=\frac{20\times4}{4}$	[2]	
			= 20	[2]	
		Velocity ratio	$=\frac{471.2}{20}$	[1]	
			= 23.6	[1]	40
				Total	80