

General Certificate of Secondary Education

Design and Technology (Systems and Control Technology) Specification

3546 Foundation

Mark Scheme

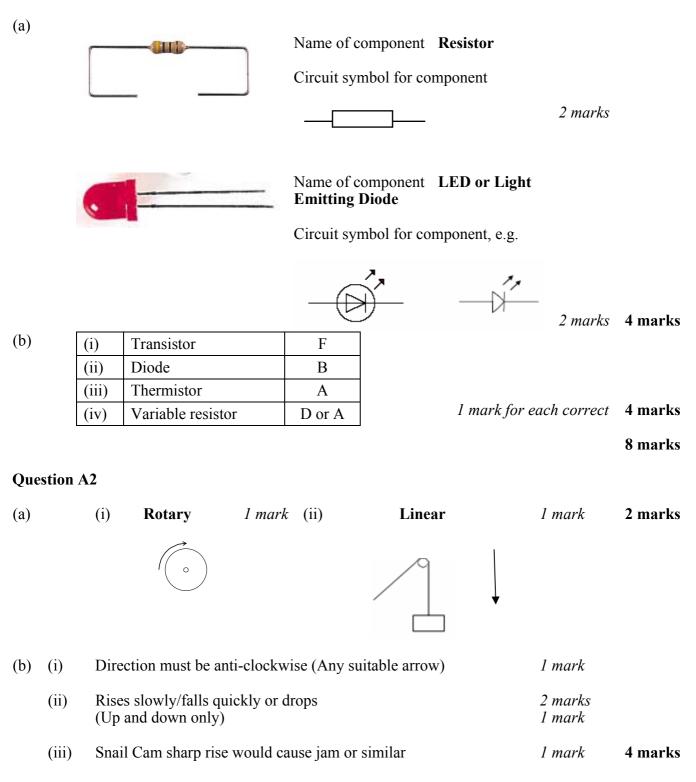
2006 examination - June series

Mark schemes are prepared by the Principal Examiner and considered, together with the relevant questions, by a panel of subject teachers. This mark scheme includes any amendments made at the standardisation meeting attended by all examiners and is the scheme which was used by them in this examination. The standardisation meeting ensures that the mark scheme covers the candidates' responses to questions and that every examiner understands and applies it in the same correct way. As preparation for the standardisation meeting each examiner analyses a number of candidates' scripts: alternative answers not already covered by the mark scheme are discussed at the meeting and legislated for. If, after this meeting, examiners encounter unusual answers which have not been discussed at the meeting they are required to refer these to the Principal Examiner.

It must be stressed that a mark scheme is a working document, in many cases further developed and expanded on the basis of candidates' reactions to a particular paper. Assumptions about future mark schemes on the basis of one year's document should be avoided; whilst the guiding principles of assessment remain constant, details will change, depending on the content of a particular examination paper.

Section A - Mechanisms

Question A1



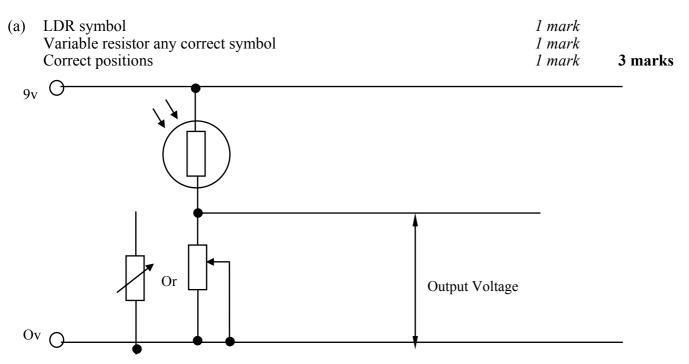
(c)		A cam that would give smooth up and down motion in a forward and backward direction e.g. Eccentric/pear cam A cam that has obvious lift up and down A cam that would not turn or would not give lift (snail cam)	3 marks 2 marks 1 mark	3 marks
(d)	(i)	Bearing/ball race/roller bearing/ball bearing	1 mark	
	(ii)	Any reference to reducing friction or allowing rotation OR axial and radial loads	1 mark	2 marks
				11 marks

(a)

(b)

(c)

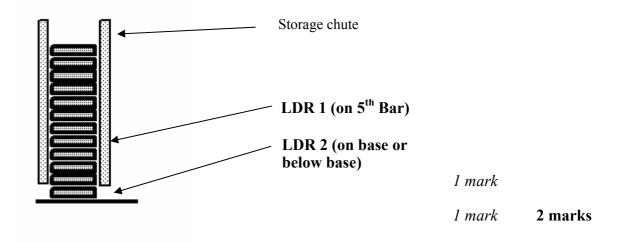
input shaft or gear		
12 teeth		
24 teeth		
(E. Vassier)	1 mark	1 mar
Simple gear train	1 mark	1 mar
Formula Gear Ratio = <u>number of teeth on driven ge</u> number of teeth on driver ge		
Correct substitution of values Gear Ratio = $\frac{24}{12}$	1 mark	
Correct answer Gear Ratio = $2:1(\frac{1}{2} \text{ or } 1:2 \text{ acceptable})$	1 mark	
2 with no calculations		3 mar
		5 mar



(b) The designer wants to use LDRs in two positions

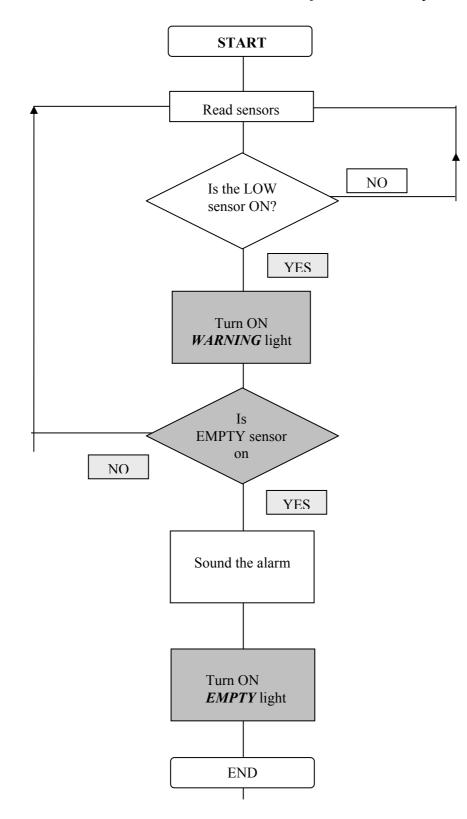
Position 1 = LDR position drawn between top of 4^{th} and bottom of 6^{th} bar

Position 2 = LDR on base level or below base



(c)

1 mark for each box completed correctly **6 marks**



11 marks

(a)	Mechanism that will move forward and return eg. Crank & Slider Mechanism that will move one way e.g. Rack and Pinion /Cam without spring return An attempt at a mechanism attached to the drawer Quality of communication (words and/or drawings) Excellent		
	Good	1 mark	6 marks
(b)	(i) Any suitable suggestion e.g. chewing gum	1 mark	
	(ii) Any realistic advantage e.g. available 24/7	1 mark	2 marks
(c)	The safety of the USER should always be considered when designing a powered mechanism.		
	Guards should ensure that you cannot START the mechanism until they are in position.		
	Most guards use a SENSOR to detect whether they are in position.		
	A belt drive can be safer for powering a mechanism because it will SLIP if something jams. A GEAR driven system will continue to exert force if there is a jam and this can result in a breakage.		
			5 marks
			13 marks

(a)	(i)	Box 1 - suitability of pulley system Two speeds fully workable pulley system with details of speed change Two speeds possible may be other mechanisms One speed eg. belt on shafts only An attempt that links the shafts	4 marks 3 marks 2 marks 1 mark	
	(ii)	Box 2 –explaining method of attachment to shaft (text or		
		sketch) A secure method that would not slip well explained e.g. taper key/pin, grubscrew, rivet, cotterpin	4 marks	
		Method that will work with possible movement e.g. parallel key/pin splines	3 marks	
		A simple method - e.g. weld/braze.	2 marks	
		An attempt e.g. glue.	1 mark	
		Quality of drawing Box 1 only		
		An understandable drawing	2 marks	
		An attempt which may be unclear	1 mark	
		Notes explaining system Box 1 only		
		Appropriate notes and explanation	2 marks	
		Minimum use of notes with vague explanation	1 mark	12 marks
(b)				
(0)		Polarity does not	ot matter	
		M _{0V}		
		Position of second switch in series	1 mark	
		Switch joins up to motor	1 mark	
		Some indication of +V and 0V	1 mark	3 marks

(c) Safety response e.g. to ensure that both hands were used to start the machine *l mark* **1 mark**

16 marks

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(a)		<i>1 mark for each appropriate rule (No duplicates t</i>	to be rewarded)	
		Keep away from hands and eyes Handle with tongs Rubber gloves Have eye wash etc. close by	2 marks	
		Goggles Machine vice Stop buttons Apron Soldering iron stand Low voltage if possible Keep hands away	2 marks	
		Avoid splashes	2 marks	6 marks
(b)	(i)	Suitability of mechanism Mechanism that will allow grip An attempt at a mechanism	2 marks 1 mark	
		Appropriate for gripping Jaws will grip and hold when user releases Jaws will grip	2 marks 1 mark	
		Quality of drawing Good clear attempt Recognisable as a jaw system	2 marks 1 mark	
	(ii)	Any appropriate reasons	1 mark for each reason	
	(iii)	Any appropriate soft metal – e.g. aluminium or named plastic e.g. polythene/nylon	1 mark	
	(iv)	Appropriate reason e.g. softer so should not mark brass	1 mark	10 marks
				16 marks

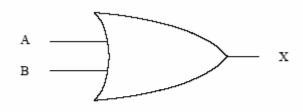
(a)	monostable	1 mark	1 mark
(b)	R1 C1 resistor 1 or capacitor	2 marks	2 marks
(c)	SW2	1 mark	1 mark
(d)	Any two appropriate methods – e.g. visit companies, use the internet, catalogues, ask other makers, etc. Any two appropriate advantages – e.g. usually time and reliability	2 marks 2 marks	4 marks
(e)	(i) 9v lamp (A)	1 mark	
	(ii) Correct voltage for circuit, low cost or similar	2 marks	3 marks
(f)	 Vac Forming process e.g. Place former in Vac Former Place and clamp sheet plastic in Vac Former Turn on heat Raise platen and former Turn on Vacuum Remove heat Turn of Vacuum Lower Platen Allow making of former (max 2 marks) 	1 mark for each relevant stage	8 marks
			19 marks

Question A	49
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(a)	Activity		CAD or CAM		
	Using computer software t circuit layout	to create a	CAD	1 mark	
	Using a milling machine to PCB	o produce a	CAM	l mark	
	Using software to test a circomputer	rcuit on a	CAD	1 mark	3 marks
(b)	А	В	Х		
	0	0	0		
	0	1	1		
	1	0	1		
	1	1	1		

(c)

1 mark for each correct response **4 marks**





(d) Robot arm is in rest position Sensor detects a box at the end of conveyor Robot arm moves into position above the box ÷ Robot arm raises and lifts box off the conveyor Robot arm lowers and grips the box Sensor detects a box at the end of conveyor Robot arm raises and lifts box off the conveyor Ŧ Robot arm releases grip on box Robot arm moves into position above the palette Robot arm lowers the box onto the palette Robot arm lowers the box onto the palette Robot arm moves into position above the box Robot arm releases grip on box Robot arm moves into position above the box Robot arm returns to the rest position

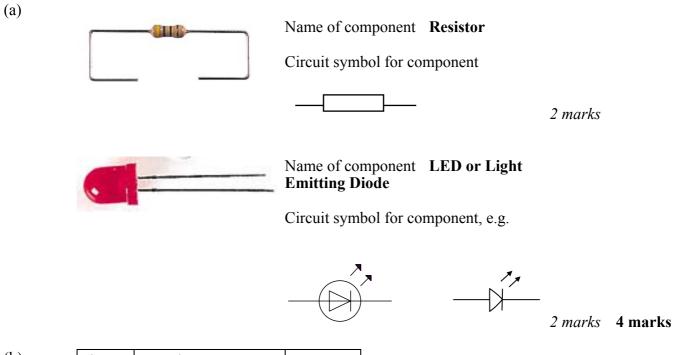
1 mark for each correct responseAccept arrows or text4 marks

Do no	ot get tired, can lift heavier weights, reliable, do not claim for		
Or ot	her suitable reason	2 marks	2 marks
e.g. h	azardous environment or high skill	2 marks	
		2 marks	4 marks
(i)	Two appropriate advantages for workers eg. safer, reduce workload, workers able to do more interesting tasks	2 marks	
(ii)	Two appropriate advantages for consumers e.g. better quality/lower priced goods	2 marks	
(iii)	One appropriate disadvantage e.g. higher start up costs, unemployment, maintenance costs, more highly skilled workforce	1 mark	5 mark
e.g. a	ble to be reprogrammed, more outputs	1 mark	
		1 mark	2 marks
			26 marks
	Do no injuri Or oth Two a e.g. h Two a e.g. e (i) (ii) (iii) (iii) Any a e.g. a Any a	 workload, workers able to do more interesting tasks (ii) Two appropriate advantages for consumers e.g. better quality/lower priced goods (iii) One appropriate disadvantage e.g. higher start up costs, unemployment, maintenance costs, 	Do not get tired, can lift heavier weights, reliable, do not claim for injuries2 marksOr other suitable reason2 marksTwo appropriate production uses for a robot e.g. hazardous environment or high skill2 marksTwo appropriate justifications e.g. expendable or more precise/cheaper to run2 marks(i)Two appropriate advantages for workers eg. safer, reduce workload, workers able to do more interesting tasks2 marks(ii)Two appropriate advantages for consumers e.g. better quality/lower priced goods2 marks(iii)One appropriate disadvantage e.g. higher start up costs, unemployment, maintenance costs, more highly skilled workforce1 markAny appropriate advantage e.g. able to be reprogrammed, more outputs Any appropriate advantage1 mark

Paper Total 125 Marks

Section B – Pneumatics

Question B1

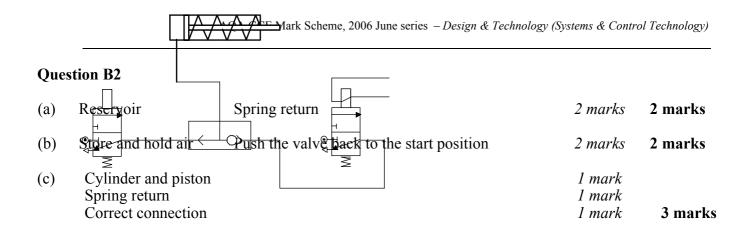


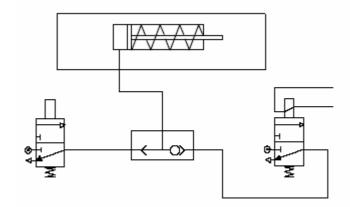
1 mark for each correct **4 marks**

8 marks

(b)

(i) Transistor		F
(ii)	Diode	В
(iii)	Thermistor	А
(iv)	Variable resistor	D





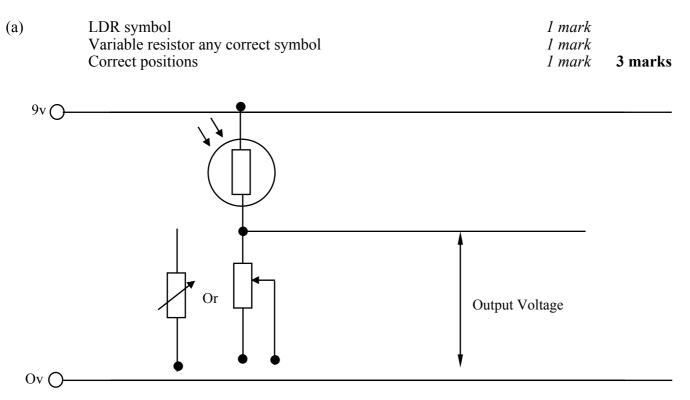
(d)	Inlet air at A	1 mark
	Outlet at B Inlet air at D	1 mark 1 mark
	Ball C moves blocking A	1 mark 4 marks

11 marks

Question B3

(a)	Cylinder B is the right hand cylinder	1 mark	1 mark
(b)	To clamp the material before a bend is applied	1 mark	1 mark
(c)	Piston out	1 mark	1 mark
(d)	Suitable methods e.g. Electro pneumatic solution Pistons not operated until guards are in place Use sensors to pick up obstructions and break circuit AND operation for safety <i>1 mark for</i>	each identified method	2 marks
			5 marks

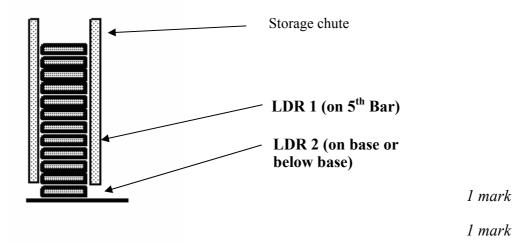
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(b) The designer wants to use LDRs as sensors in two positions

Position 1 = LDR position drawn between top of 4^{th} and bottom of 6^{th} bar

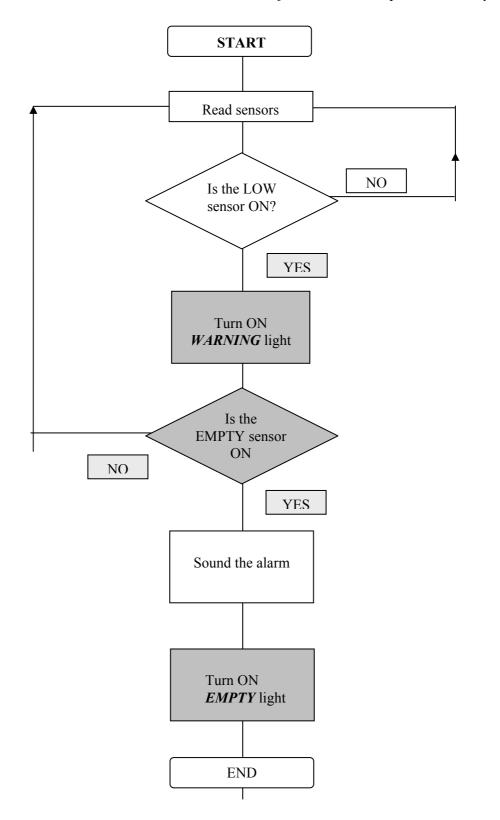
Position 2 = LDR on base level or below base



2 marks

(c)

1 mark for each box completed correctly **6 marks**





(a)	Pneumatic system capable of moving both ways Will move one way eject chocolate bar Will move An attempt at a pneumatic system		4 marks 3 marks 2 marks 1 mark	
	Quality of communication (words and/or drawings)	Excellent Good	2 marks 1 mark	6 marks
(b)	(i) ANY suitable suggestion e.g. chewing gum		1 mark	
	(ii) Any realistic advantage e.g. available 24/7		1 mark	2 marks
(c)) The safety of the USER should always be considered when designing a pneumatic system.			
	Guards should ensure that you cannot START the pressure until they are in position.			
	Most guards use a SENSOR to detect whether they a			
	A LOW pressure pneumatics system would be safer because it will stop if something jams.		1 mark for each	
	A HIGH pressure pneumatics system will continue to if there is a jam and this can result in a breakage	each appropriate response	5 marks	
				13 marks

(a)	Attaching cylinder to hacksaw frame Wholly appropriate method of fixingclevis/pin, bolt screw/ rivet An attempt at fixing cylinder or piston braze/weld not glue		l mark I mark 2 marks	5
(b)	Suitable ends for the 3 port valves Roller valve – first valve Button – second valve Drawn correctly		! mark ! mark ! mark	
	Correctly completed cylinder Piston in position to activate both valves Suitable end to piston		l mark	
	No spring inside – double acting Quality of drawing		! mark ! mark ! mark	
	Correct connections Connection from LHS of cylinder to 5PV Connection from RHS of cylinder to 5PV Both connections to the same window	i i i i i i i i i i i i i i i i i i i	l mark l mark l mark 10 mark	KS
(c)	• • • • · · · · · · · · · · · · · · · ·			
	0V	Polarity does 1	not matter	
	Position of second switch in series Switch joins up to solenoid Some indication of +V/0V	1 mark 1 mark 1 mark	3 marks	
(d)	So that they could not be operated unless both hands were used	1 mark	1 mark	
			16 marks	

(a)		1 mark for each appropriate rule (No duplicates to	1 mark for each appropriate rule (No duplicates to be rewarded)			
		Keep away from hands and eyes Handle with tongs Rubber gloves Have eye wash etc. close by	2 marks			
	44.40	Goggles Machine vice Stop buttons Apron Soldering iron stand	2 marks			
	ě.	Low voltage if possible Keep hands away Avoid splashes	2 marks	6 marks		
(b)	(i)	Suitability of pneumatic system A pneumatic system that will allow grip An attempt at a pneumatic system	2 marks 1 mark			
		Appropriate for gripping brass bar Jaws will grip and hold when user releases Jaws will grip	2 marks 1 mark			
		Quality of drawing Good clear attempt Recognisable as a jaw system	2 marks 1 mark			
	(ii)	Any appropriate reasons eg. non slip/justify grip method	1 mark for each reason			
	(iii)	Any appropriate soft metal – e.g. aluminium or named plastic e.g. polythene/nylon	1 mark			
	(iv)	Appropriate reason e.g. softer so should not mark brass	1 mark	10 mark		
				16 marks		

(a)	mono	stable	1 mark	1 mark
(b)	R1	C1 resistor 1 or capacitor	2 marks	2 marks
(c)	SW2		1 mark	1 mark
(d)	e.g. v ask o Any t	wo appropriate methods – isit companies, use the internet, catalogues, ther makers, etc. wo appropriate advantages – sually time and reliability	2 marks 2 marks	4 marks
(e)	(i)	9v lamp (A)	1 mark	
	(ii)	Correct voltage for circuit, low cost or similar	2 marks	3 marks
(f)		 Vac Forming process e.g. 9. Place former in Vac Former 10. Place and clamp sheet plastic in Vac Former 11. Turn on heat 12. Raise platen and former 13. Turn on Vacuum 14. Remove heat 15. Turn of Vacuum 16. Lower Platen Allow making of former (max 2 marks)	l mark for each relevant stage	8 marks 19 marks



2				
(a)	Activity	CAD or CA	M	
	Using computer software to create a circuit layout	CAD	1 mark	
	Using a milling machine to produce a PCB	САМ	1 mark	
	Using software to test a circ on a computer	cuit CAD	1 mark	3 marks
(b)	A 0 0 1 1	B 0 1 0 1	X 0 1 1 1	
		l for ea	ach correct response	e 4 marks
(c)	AB	,	x	
	Symbol Labels Inputs and output		1 mark 1 mark	2 marks
	(d)	Sens	ot arm is in rest position or detects a box at the end of arm moves into position	
	Robot arm raises and lifts box off the conveyo		t arm lowers and grips the	
	Sensor detects a box at the end of convevor		ot arm raises and lifts box	off the conveyor
	Robot arm releases grip on box		t arm moves into position :	
	Robot arm lowers the box onto the palette		ot arm lowers the box ont	
	Robot arm moves into position above the box	\neg \searrow	ot arm releases grip on bo	
		Robe	of arm moves into position :	above the box

1 mark for each correct response Accept arrows or text **4 marks**

(e)	Two suitable reasons e.g.Do not get tired, can lift heavier weights, reliable, do not claim for injuriesOr other suitable reason2 model			2 marks
(f)	e.g. h Two a	appropriate uses for a robot azardous environment or high skill appropriate justifications spendable or more precise/cheaper to run	2 marks 2 marks	4 marks
(g)	(i)	Two appropriate advantages for workers e.g. safer, reduce workload, workers able to do more interesting tasks	2 marks	
	(ii)	Two appropriate advantages for consumers e.g. better quality/lower priced goods	2 marks	
(b)	(iii)	One appropriate disadvantage e.g. higher start up costs, unemployment, maintenance costs, more highly skilled workforce.	1 mark	5 marks
(h)	e.g. al	appropriate advantage ble to be reprogrammed more outputs	1 mark	
		appropriate advantage maller component count	1 mark	2 marks
				26 marks

Paper Total 125 marks