GCE 2004 June Series



Mark Scheme

Mathematics and Statistics B *MBM6*

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Key to Mark Scheme

M	mark is for	method
m	mark is dependent on one or more M marks and is for	method
A	mark is dependent on M or m marks and is for	accuracy
В	mark is independent of M or m marks and is for	accuracy
E	mark is for	explanation
$\sqrt{\text{or ft or F}}$		follow through from previous
		incorrect result
cao		correct answer only
cso		correct solution only
awfw		anything which falls within
awrt		anything which rounds to
acf		any correct form
ag		answer given
sc		special case
oe		or equivalent
sf		significant figure(s)
dp		decimal place(s)
A2,1		2 or 1 (or 0) accuracy marks
–x ee		deduct x marks for each error
pi		possibly implied
sca		substantially correct approach

Abbreviations used in Marking

MC-x	deducted x marks for mis-copy
MR-x	deducted x marks for mis-read
isw bod	ignored subsequent working
bod	given benefit of doubt
wr	work replaced by candidate
fb	formulae book

Application of Mark Scheme

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Correct answer without working	mark as in scheme		
Incorrect answer without working	zero marks unless specified otherwise		
More than one method / choice of solution:			
2 or more complete attempts, neither/none crossed out	mark both/all fully and award the mean mark rounded down		
1 complete and 1 partial attempt, neither crossed out	award credit for the complete solution only		
Crossed out work	do not mark unless it has not been replaced		
Alternative solution using a correct or partially correct method	award method and accuracy marks as appropriate		

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Question Number	Solution	Marks	Total	Comments
and Part				
1	At time t , let the cylinder have rolled a distance x down the inclined plane and have an angular velocity of ω . The speed of the centre of the cylinder is v where $v = r\omega$ Since the cylinder does not slide $v = \dot{x} = r\dot{\theta} = r\omega$	B1		
	Using forces and $G = I\ddot{\theta}$			Alternatively using energy The kinetic energy of the cylinder is the kinetic energy of the linear motion of the centre of mass of the cylinder plus the
	Using $F = ma$ along the inclined plane	M1		rotational kinetic energy of the cylinder $= \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2$ $= \frac{1}{2}m(r\omega)^2 + \frac{1}{2}\times\frac{1}{2}mr^2\times\omega^2$
	$ma = mg \sin \alpha - F$	A1		$= \frac{3}{4}mr^2\omega^2$
	Using $G = I\ddot{\theta}$ about O , the centre of the			
	cylinder,	M1		By conservation of energy,
	$Fr = \frac{1}{2}mr^2\ddot{\theta} = \frac{1}{2}mr^2\dot{\omega}$	A1		$mg x \sin \alpha = \frac{3}{4} mr^2 \omega^2 = \frac{3}{4} mv^2$
	$F = \frac{1}{2}mr\dot{\omega}$			
	Since $v = \dot{x} = r\dot{\theta} = r\omega$, $a = r\dot{\omega}$			Differentiating with respect to x ,
	$ma = mg \sin \alpha - \frac{1}{2} mr\dot{\omega}$	M1		$mg\sin\alpha = \frac{\mathrm{d}}{\mathrm{d}x}(\frac{3}{4}mv^2)$
	$\frac{3}{2} ma = mg \sin \alpha$			$= \frac{\mathrm{d}}{\mathrm{d}v} \left(\frac{3}{4} m v^2 \right) \frac{\mathrm{d}v}{\mathrm{d}t} \frac{\mathrm{d}t}{\mathrm{d}x}$
				$= \frac{3}{2}mv \times a \times \frac{1}{v}$
				$=\frac{3}{2}ma$
	$a = \frac{2}{3}g\sin\alpha$	A1	7	$\therefore a = \frac{2}{3}g\sin\alpha$
	Total		7	

Question	Solution	Marks	Total	Comments
Number				
and Part				
2 (a)(i)	$r\dot{\theta} = \frac{r^2\dot{\theta}}{r}$	M1		
	$= \frac{4}{\frac{4}{4+\cos\theta}}$			
	$=4+\cos\theta$	A1	2	
(ii)	$\dot{r} = \frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{4}{4 + \cos \theta} \right)$	M1		Allow for $\frac{d}{d\theta} \left(\frac{4}{4 + \cos \theta} \right)$
	$= \frac{4\sin\theta}{\left(4+\cos\theta\right)^2}\dot{\theta}$	M1		
	$= \frac{4\sin\theta}{(4+\cos\theta)^2} \frac{4+\cos\theta}{\frac{4}{4+\cos\theta}}$			
	$= \sin \theta$	A1	3	
(b)	Transverse velocity, $r\dot{\theta}$, is $4 + \cos\theta$			
	Radial velocity is $\sin \theta$			
	Magnitude of velocity is			
	$\sqrt{(4+\cos\theta)^2+(\sin\theta)^2}$	M1		
	$=\sqrt{17+8\cos\theta}$	A1	2	
	Total		7	

Question	Solution	Marks	Total	Comments
Number and Part				
3(a)	Consider ring shown	M1		
	Str.			
	$\delta I = 2\rho \pi x \delta x . x^2$ $= 2\pi \rho x^3 \delta x$			
	$\frac{\mathrm{d}I}{\mathrm{d}x} = 2\pi\rho x^3$	A1		
	$I = \int_0^a 2\pi \rho x^3 \mathrm{d}x = \pi \rho \frac{a^4}{2}$	M1		
	$= \frac{1}{2} ma^2 \left[\text{using } m = \pi a^2 \rho \right]$	A1 B1	5	For $m = \pi a^2 \rho$
(b)(i)	M of I of rod about centre is $\frac{1}{3}m(3a)^2 = 3ma^2$	B1		
	M of I of rod about C is $3ma^2 + m(2a)^2 = 7ma^2$ M of I of disc about centre is	B1		
	$\frac{1}{2}4m(2a)^2 = 8ma^2$	B1		
	M of I of disc about C is $8ma^2 + 4m(7a)^2$	M1		
	= $204ma^2$ M of I of compound pendulum is $211ma^2$	A1 A1	6	
(ii)	Using $G = I\ddot{\theta}$,	M1		
	$211 \ ma^2 \ddot{\theta} = -mg.2a \sin \theta - 4mg.7a \sin \theta$ $= -30mga\theta \text{[for small angles]}$	A1 A1		
	$\ddot{\theta} = -\frac{30g}{211a}\theta$	A1		cao
	Period is $2\pi \sqrt{\frac{211a}{30g}}$	A 1√	5	ft from $\ddot{\theta}$ above
				Accept $\frac{2\pi}{\sqrt{\frac{30g}{211a}}}$
	Or			sc 4 if correct except no '-' sign in lines 2,3,4
	C of G 6a	(M1 A1)		
	Periodic time is $2\pi \sqrt{\frac{211a^2}{5g.6a}}$	(M1 A1)		
	$= 2\pi \sqrt{\frac{211a}{30g}}$	(A1)		
	Total		16	
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Question	Solution	Marks	Total	Comments
Number				
and Part 4 (a)	Distance of particle below <i>B</i> is			
	$4a - a - 2a\cos\theta$	M1		
	$=3a-2a\cos\theta$	A1		
	P.E. = $-mg(3a - 2a\cos\theta)$: PE of system is			
	$-2mg\frac{a}{2}\cos 2\theta - mg(3a - 2a\cos\theta)$	M1		
	$= -mga(\cos 2\theta + 3 - 2\cos \theta)$	A1	4	sc 3 if energy not taken to be zero at B
(b)	$\frac{\mathrm{d}V}{\mathrm{d}\theta} = 2mga\sin 2\theta - 2mga\sin \theta$	M1 A1		
	= 0 ⇒			
	$2\sin 2\theta - 2\sin \theta = 0$	M1		
	$4\sin\theta\cos\theta - 2\sin\theta = 0$	A 1		
	$\sin\theta(2\cos\theta - 1) = 0$	A1		
	$\theta = 0 \text{ or } \frac{\pi}{3}$	A1		
	$\frac{\mathrm{d}^2 V}{\mathrm{d}\theta^2} = 4mga\cos 2\theta - 2mga\cos \theta$	M1		
	When $\theta = 0$, this gives stable equilibrium	A1		
	When $\theta = \frac{\pi}{3}$,			
	this gives unstable equilibrium.	A1	8	
	Total		12	

Question Number	Solution	Marks	Total	Comments
and Part				
5(a)				
	$\begin{vmatrix} 2a & \downarrow \\ \rightarrow i \end{vmatrix}$			
	$C \xrightarrow{2a} B$			
	C of G by symmetry, using \mathbf{i} and \mathbf{j} as shown relative to C ,			
	C of G of combined body is $\frac{3}{2}a\mathbf{i} + \frac{a}{2}\mathbf{j}$	M1 A1		
	In equilibrium position, line joining A to this point is vertical			
(b)(i)	$\therefore \tan \phi = \frac{1}{3}$ M of I of rod about axes through A is	M1 A1	4	
	$\frac{4}{3}.3ma^2 = 4ma^2$	B1		
	M of I of rod BC is $\frac{1}{3}.3ma^2 + 3m\left(\sqrt{5a^2}\right)^2 = 16ma^2$	241 4 1		Condona $\frac{4}{3} 2ms^2 + 2m(2s)^2$
	$\left(\frac{1}{3}.3ma + 3m\right) = 16ma$	M1A1		Condone $\frac{4}{3} .3ma^2 + 3m(2a)^2$
	\therefore M of I of system is $20ma^2$	B1 A1	5	For $\sqrt{5} a$
(ii)	When AG is vertical by conservation of energy, where G is the centre of mass,			
	$\frac{1}{2}20ma^2\dot{\theta}^2 = 3mga + 6mg. \frac{\sqrt{10}}{2}a$	M1A1 M1		LHS
		A1		RHS 2 terms, one 3mga
				Or RHS Change in PE of C of G $6mg. \frac{a}{2}(1 + \sqrt{10})$
	$\therefore \dot{\theta}^2 = \frac{3g(1+\sqrt{10})}{10a}$	A1	5	
(iii)	Vertical reaction at hinge is $Mg + Mh \dot{\theta}^2$	M1		Either
	$\therefore \text{ Reaction is } 6m.g + 6m. \frac{\sqrt{10}}{2} a \cdot \dot{\theta}^2$	M1 A1		Both
	$= 6mg + 6m. \frac{\sqrt{10}}{2}a \frac{3g(1+\sqrt{10})}{10a}$	A1	4	sc 1 for 6mg
	$= \frac{150 + 9\sqrt{10}}{10} mg \text{ or } (15 + \frac{9}{10}\sqrt{10}) mg$			
	Total		18	
	TOTAL		60	