

Mathematics

Advanced GCE 4764

Mechanics 4

Mark Scheme for June 2010

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1(i)

$$(m - |\delta m|)(v + \delta v) + |\delta m|(v - u) - mv = -mg\delta t$$

M1 Impulse = change in momentum

A1 Accept sign errors in δm

$$m\delta v - u|\delta m| - |\delta m|\delta v = -mg\delta t$$

$$m\frac{\delta v}{\delta t} + u\frac{\delta m}{\delta t} + \delta m\frac{\delta v}{\delta t} = -mg$$

M1 Form DE

$$\Rightarrow m\frac{dv}{dt} + u\frac{dm}{dt} = -mg$$

E1 Complete argument (including signs)

4

$$(ii) \quad \frac{dm}{dt} = -k \Rightarrow m = m_0 - kt$$

M1

$$\text{So } (m_0 - kt)\frac{dv}{dt} - uk = -(m_0 - kt)g$$

A1

$$\frac{dv}{dt} = \frac{uk}{m_0 - kt} - g$$

$$v = \int \left(\frac{uk}{m_0 - kt} - g \right) dt$$

M1 Integrate

$$= -u \ln(m_0 - kt) - gt + c$$

A1

$$t = 0, v = 0 \Rightarrow 0 = -u \ln m_0 + c$$

M1 Use condition

$$v = -u \ln \left(1 - \frac{k}{m_0} t \right) - gt$$

A1

$$\text{Fuel burnt when } m_0 - kt = 0.25m_0$$

M1

$$v = -u \ln 0.25 - \frac{0.75m_0 g}{k}$$

A1

8

<p>2(i)</p>	$m \frac{dv}{dt} = -mkv^{\frac{3}{2}}$ $\int -v^{-\frac{3}{2}} dv = \int k dt$ $2v^{-\frac{1}{2}} = kt + c$ $t = 0, v = 25 \Rightarrow c = \frac{2}{5}$ $2v^{-\frac{1}{2}} = kt + \frac{2}{5}$ $v = 4 \left(kt + \frac{2}{5} \right)^{-2}$	<p>M1 N2L</p> <p>A1</p> <p>M1 Separate and integrate</p> <p>A1</p> <p>M1 Use condition</p> <p>M1 Rearrange</p> <p>E1</p>	<p>7</p>
<p>(ii)</p>	$x = \int 4 \left(kt + \frac{2}{5} \right)^{-2} dt$ $= -\frac{4}{k} \left(kt + \frac{2}{5} \right)^{-1} + A$ $t = 0, x = 0 \Rightarrow A = \frac{10}{k}$ $x = \frac{1}{k} \left(10 - \frac{4}{kt + \frac{2}{5}} \right)$	<p>M1 Integrate</p> <p>M1 Use condition</p> <p>A1</p>	<p>3</p>
<p>(iii)</p>	<p>The speed decreases, tending to zero</p> <p>The displacement tends to $\frac{10}{k}$</p>	<p>B1</p> <p>B1 Cv (10/k)</p>	<p>2</p>

3(i)	$V = -mga \sin \theta + \frac{\lambda}{2(2a)} (3a \sin \theta)^2$	M1	GPE term
		M1	EPE term
		A1	
	$\frac{dV}{d\theta} = -mga \cos \theta + \frac{\lambda}{4a} \cdot 9a^2 \cdot 2 \sin \theta \cdot \cos \theta$	M1	Differentiate
		A1	
	$= a \cos \theta \left(\frac{9}{2} \lambda \sin \theta - mg \right)$	E1	
6			
(ii)	$\frac{dV}{d\theta} = 0 \Leftrightarrow \cos \theta = 0 \text{ or } \sin \theta = \frac{2mg}{9\lambda}$	M1	Solve $\frac{dV}{d\theta} = 0$
(A)	$\lambda > \frac{2}{9} mg$		
	$\theta = \frac{\pi}{2}$	A1	
	and $\theta = \sin^{-1} \frac{2mg}{9\lambda}$	A1	
	$\frac{d^2V}{d\theta^2} = -a \sin \theta \left(\frac{9}{2} \lambda \sin \theta - mg \right) + a \cos \theta \left(\frac{9}{2} \lambda \cos \theta \right)$	M1	Second derivative (or other valid method)
		A1	Any correct form
	$= a \left(\frac{9}{2} \lambda (1 - 2 \sin^2 \theta) + mg \sin \theta \right)$		
	$V'' \left(\frac{\pi}{2} \right) = a \left(-\frac{9}{2} \lambda + mg \right) < 0$	M1	Substitute $\theta = \frac{\pi}{2}$
	\Rightarrow unstable	A1	Deduce unstable
	$V'' \left(\sin^{-1} \left(\frac{2mg}{9\lambda} \right) \right) = a \left(\frac{9}{2} \lambda \left(1 - 2 \left(\frac{2mg}{9\lambda} \right)^2 \right) + \frac{2(mg)^2}{9\lambda} \right)$	M1	Substitute other value

	$= \frac{9}{2} \lambda a \left(1 - \left(\frac{2mg}{9\lambda} \right)^2 \right)$		
	$\lambda > \frac{2}{9} mg \Rightarrow \left(\frac{2mg}{9\lambda} \right)^2 < 1 \Rightarrow V'' > 0$	M1	Consider second derivative
	$\Rightarrow \text{stable}$	A1	Complete argument
			10
(B)	$\lambda < \frac{2}{9} mg \Rightarrow$	M1	Consider solutions
	$\theta = \frac{\pi}{2} \text{ only}$	A1	
	$V'' \left(\frac{\pi}{2} \right) = a \left(-\frac{9}{2} \lambda + mg \right) > 0$	M1	Consider second derivative
	$\Rightarrow \text{stable}$	A1	Complete argument
			4
(C)	$\lambda = \frac{2}{9} mg \text{ gives } \theta = \frac{1}{2} \pi \text{ only (from both factors)}$	M1	Consider solutions
		A1	
	$V'' \left(\frac{\pi}{2} \right) = 0$		
	$V' \left(\frac{\pi}{2} - \epsilon \right) = (+)(-) = (-)$		
	$V' \left(\frac{\pi}{2} + \epsilon \right) = (-)(+) = (+)$	M1	Valid method
	Hence stable	A1	Complete argument
			4

4(i)	Mass of slice $\approx \rho \pi y^2 \delta x$	M1	
	So $I_{\text{slice}} \approx \frac{1}{2} (\rho \pi y^2 \delta x) y^2$	M1	
	$= \frac{1}{32} \rho \pi x^4 \delta x$	A1	
	So $I_{\text{cone}} \approx \int_0^{2a} \frac{1}{32} \rho \pi x^4 dx$	M1	
	$= \left[\frac{1}{160} \rho \pi x^5 \right]_0^{2a}$	A1	ft
	$= \frac{1}{5} \pi \rho a^5$	A1	
	$\rho = \frac{M}{\frac{2}{3} \pi a^3}$	M1	
	$\Rightarrow I_{\text{cone}} = \frac{3}{10} M a^2$	E1	
			8
(ii)	Mass of small cone $= \left(\frac{1}{2}\right)^3 M = \frac{1}{8} M$		
	Mass of frustum $= \frac{7}{8} M$	B1	
	$I_{\text{large cone}} = I_{\text{small cone}} + I$	M1	
	$\frac{3}{10} M a^2 = \frac{3}{10} \left(\frac{1}{8} M\right) \left(\frac{1}{2} a\right)^2 + I$	M1	Moment of inertia of small cone
	$\Rightarrow I = \frac{93}{320} M a^2$		
	$\frac{7}{8} M = 2.8, a = 0.1 \Rightarrow I = 0.0093$	E1	
			4

<p>(iii) $C = I\bar{\theta} \Rightarrow \bar{\theta} = \frac{0.05}{0.0093}$</p> <p>$t = \frac{10}{\bar{\theta}} = 1.86$</p>	<p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p>	<p>4</p>
<p>(iv) Centre of mass:</p> <p>$\frac{7}{8}M\bar{x} + \frac{1}{8}M \cdot \frac{3a}{4} = M \cdot \frac{3a}{2}$</p> <p>$OG = \bar{x} = \frac{45a}{28} = \frac{4.5}{28} \approx 0.1607$</p> <p>i.e. G is $\frac{1.7}{28} \approx 0.0607$ m from the small circular face</p>	<p>M1</p> <p>A1</p> <p>A1 Any distance which locates G</p>	<p>3</p>
<p>(v) $0.1J = I(10 - 5)$</p> <p>$J = 0.465$</p> <p>Radius at G is $\frac{1}{2}\bar{x}$</p> <p>$\left(\frac{4.5}{56}\right)J = I(5 - \omega)$</p> <p>$\Rightarrow \omega = \frac{55}{56} \approx 0.98$</p>	<p>M1 Moment of impulse = ang. momentum</p> <p>A1</p> <p>B1</p> <p>M1 Moment of impulse = ang. momentum</p> <p>A1</p>	<p>5</p>

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